



SIMPLE & SMART



Line of products of ALPHA5 Series

Servo Amplifier

			Comman	d interface)		Contro	l mode		Power		_	Applicable
Model		Pulse/ analog	Di/Do	Modbus -RTU	SX bus	Positioning	Position	Speed	Torque	supply	Capacity	Type	motor series
P4 19										Single- phase or 3-phase 200 to 240 VAC	0.05 to 0.75kW	RYT***□5-VV2	GYS GYC
9	VV type	•	•	•		•	•	•	•	3-phase 200 to 240 VAC	0.85 to 5.0kW	HYI LD-VV2	GYG
General-purpose interface										Single- phase 100 to 120 VAC	0.05 to 0.375kW	RYT***□5-VV6	GYS
	VS type				•		•	•	•	Single- phase or 3-phase 200 to 240 VAC	0.05 to 0.75kW	RYT***□5-VS2	GYS
9	7.									200 to	0.85 to 5.0kW	RYT***□5-LS2	GYC GYG
13										240 VAC	J.ORVV		
High speed serial bus (SX bus)	LS type				•	•	•			Single- phase 100 to 120 VAC	0.05 to 0.375kW	RYT***□5-VS6 RYT***□5-LS6	GYS

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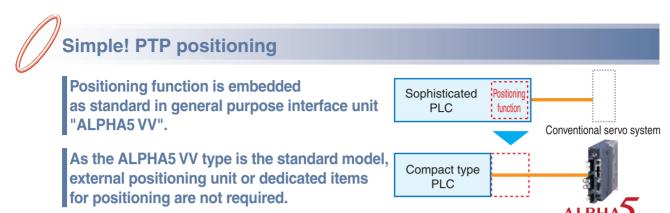
Next generation servo system for ever-evolving machines

Servomotor

Model	Rated speed	Power	Rated output	Servomotor type		Protective	Francis	Type
iviodei	(max. speed)	supply	capacity	Without brake	With brake	constructon	Encoder	туре
6	2000 ()	200V	11 types			IP67 *1	18-bit ABS/INC	GYS***D5-HB2(-B) *2
	3000r/min /0.75kW or less: 6000r/min 1.0kW or more: 5000r/min	series	0.05 to 5.0kW			1667 1	20-bit INC	GYS***D5-RB2(-B) *2
GYS motor Ultra-low inertia		100V series	4 types 0.05 to 0.375kW	•	•	IP67 *1	18-bit ABS/INC 20-bit INC	GYS***D5-HB6(-B) *2 GYS***D5-RB6(-B) *2
	3000r/min /0.75kW or less: 6000r/min	200V	7 types			IP67 *1	18-bit ABS/INC	GYC***D5-HB2(-B) *2
GYC motor Low inertia	1.0kW or more: 5000r/min	series	0.1 to 2.0kW			0.	20-bit INC	GYC***D5-RB2(-B) *2
	2000r/min	200V	5 types			IP67 *1	18-bit ABS/INC	GYG***C5-HB2(-B) *2
GYG motor Middle inertia	(3000r/min) series	series	9S 0.5 to 2.0kW			11 07 1	20-bit INC	GYG***C5-RB2(-B) *2
	1500r/min	200V	3 types 0.5, 0.85,			IP67 *1	18-bit ABS/INC	GYG***B5-HB2(-B) *2
GYG motor Middle inertia	(3000r/min) series		1.3kW			IFO/ 1	20-bit INC	GYG***B5-RB2(-B) *2

^{*1:} Except for shaft-through part (and connectors for GYS and GYC motors of 0.75kW or less). *2: Models with a brake has "-B" at the end.

Compatibility with general-purpose communication: VV type



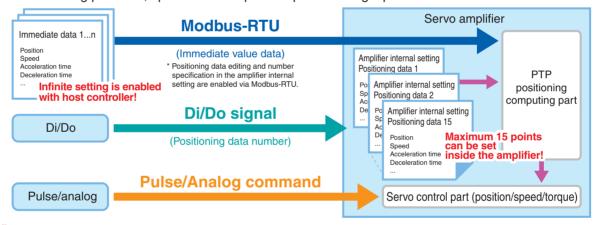
with positioning function



3 in 1!

Following operations are enabled by one unit:

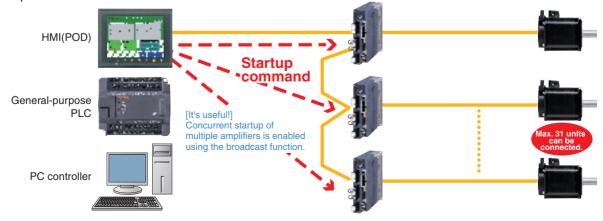
- Positioning via Modbus-RTU communications (immidiate value data)
- Positioning via Di/Do signal (positioning data 15 points*)
- Controlling positions, speeds and torques via pulse/analog input





Simple connection! Modbus-RTU communications

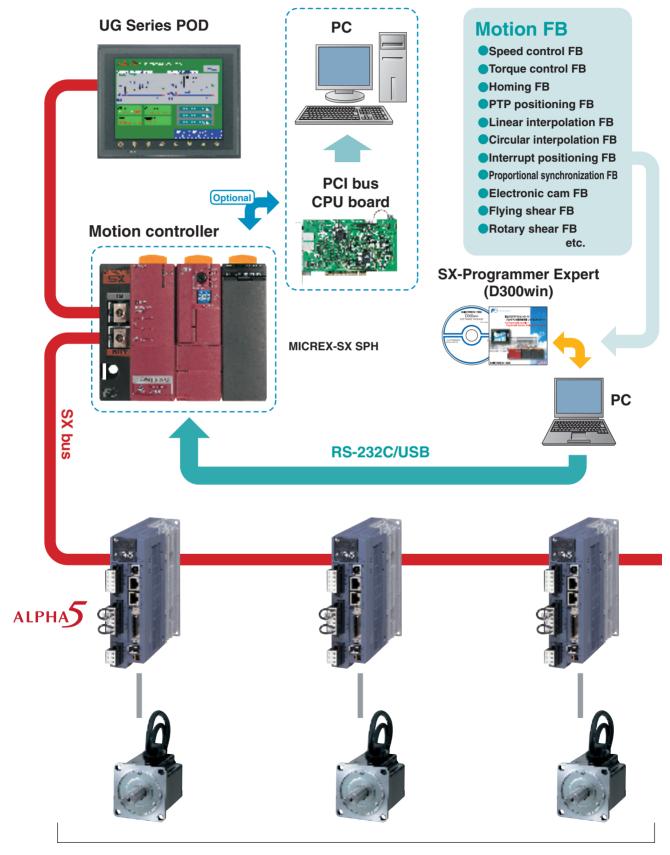
Operations such as PTP positioning operation, parameter edit, and various monitoring are enabled. All you need to do is connect HMI (POD), general-purpose PLC, or PC controller directly to servo amplifier via Modbus-RTU communications.



Other makers' products compatible with Modbus-BTU

Compatibility with SX bus: VS type and LS type

Sophisticated motion control system that has synchronization and interpolation controls can be configured easily.





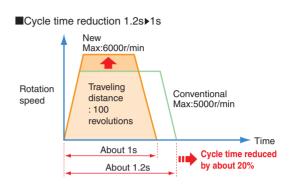
Fast and accurate positioning is realized.

New high speed servo control engine Frequency response 1500Hz

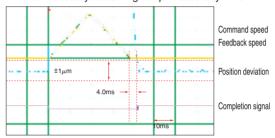
Increased motor rotation speed Max. rotation speed 6000r/min

Fine resolution encoder
18-bit absolute/incremental 262,144 pulses
20-bit incremental 1,048,576 pulses

High performance frequency response (1500Hz), high rotation speed (6000r/min) and high resolution encoder reduce the cycle time and make faster and more accurate positioning and settling possible.



■Time necessary to settling to 1μ m accuracy 4ms



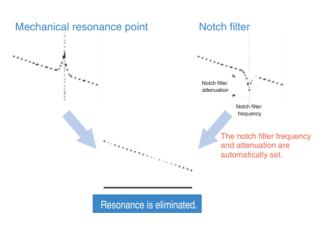
1/10000 rotation accuracy with a 10mm ball screw = 1μ m



New control functions

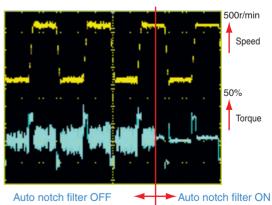
New notch filter (auto notch filter)

The notch filter is set automatically upon detection of mechanical resonance. Because detection and calculation are always conducted while the auto notch filter remains turned on, resonance frequencies changing by time are effectively filtered.





Wire saving can be achieved with elimination of the limit switch and over travel signal. Moreover, several homing functions allows homing program creation to be simplified only by combining the servo parameters. Creating complicated program of homing in the host controller is no more necessary.



Motor stop method setting is enabled

- Alarm occurrence
- Main power supply is OFF.
- Servo ON signal is OFF.

Selection among rapid deceleration stop, DB stop, and coast-to-stop is enabled under the above conditions. Since limiting output torque at desired value is possible even if rapid deceleration stops is selected, impact shock to the machine can be reduced.

^{*} However, it is enabled when the control power supply is input.



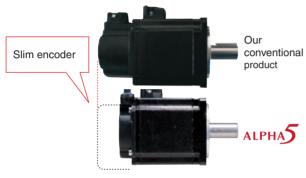
Size reduction of servomotor and servo amplifier

- Servo amplifier

The installation area is reduced by 25 to 30% when compared with our conventional model.

- Servomotor

The overall length is reduced by about 15% when compared with our conventional model.



(Comparison with 0.2kW GYS motor)

Long life design

The designed service lives of various parts of the servo amplifier are extended.

Electrolytic capacitor: 10 years Cooling fan: 10 years

- * Operating conditions
 - Ambient temperature: Average 30°C/year
- Load factor: Within 80%
- Operation ratio: Within 20 hours/day

Compliance with various standards

Compliance with CE marking and UL/cUL

The standard model complies with CE marking and UL/cUL.





Compliance with RoHS directive

The standard model complies with EU's specific hazardous material limitation (RoHS) directive. The servo system is environmentally friendly because use of six hazardous materials is limited.

<Six hazardous materials>

Lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyl (PBB), polybrominated diphenylether (PBDE)

Close installation

The servo amplifier can be installed side by side without a clearance. The installation space in the control panel of the machine is reduced.

* 80% ED rating in case of close installation
There is no limitation if 5mm or a larger clearance is placed.



Close installation can be made even if the ABS backup battery is installed.

The battery can be replaced without difficulty while the servo amplifier is left installed.



The designed life time of the battery is about 35000 hours. (Retention time with power turned off)



Environmental resistance

IP67 (servomotor)

The standard servomotor model is compatible with IP67* and it can be used in the environment susceptible to water or dust splashes.

* Except for shaft-through part and connectors



Compatibility with FALDIC- α , - β and -W motors

Because compatibility with FALDIC- α , - β and -W Series servomotors is assured, the new amplifier meets requirements for replacement of existing products flexibly. (Compatibility with individual products is planned.)

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Improved usability: PC Loader

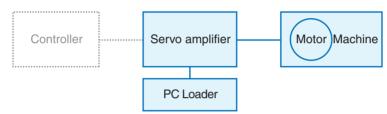
USB connection

The amplifier can be connected to PC using a commercially available USB cable (B-type).

Simple setup

- Easy tuning and profile operation

Because the servo can be adjusted for the machine even if the controller program is not completed, the machine setup time is substantially reduced.



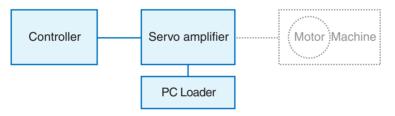
Easy tuning data entry screen



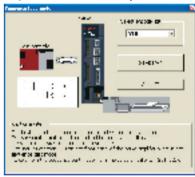
Up to 25 reciprocal motions of the servomotor are conducted while the gain is automatically adjusted.

- Sequence test mode

The controller program can run even if the machine is not completed. The efficiency of program debugging is improved.



Sequence test mode data entry screen



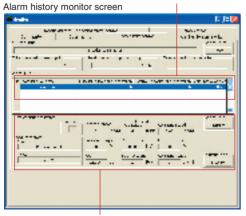
The sequence of the host controller can be tested even if the servomotor is not connected.

Enriched maintenance functions

- Functions associated with alarm

When an alarm occurs, data such as the speed and torque at alarm occurrence is displayed as well as the description of the alarm. Accurate analyses into the cause of the alarm are possible.

Description of the alarm and various cumulative operation times are displayed.



Each piece of data at alarm occurrence is displayed.

- Life warning function

The life of consumable parts of the servo amplifier is calculated.

- Battery life warning
- Main circuit capacity life warning
- Cooling fan life warning

Warning monitor screen

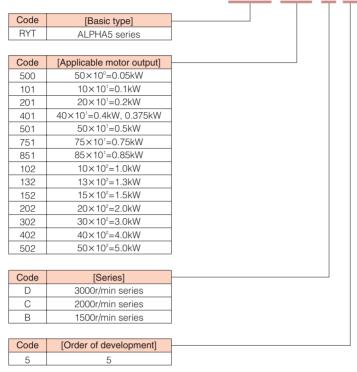


The warning can be issued in a sequence output signal or displayed on the keypad.

Explanation of Model Codes

Servo amplifier

RYT 500 D 5 - V S 2



Code	[Input voltage]
2	3-phase 200 VAC
6	Single-phase 100 VAC

Code	[Upper interface]
S	SX bus
V	General-purpose interface (pulse, analog voltage)

Code	[Major functions]
V	Position, speed and torque control
L	Built-in positioning function

Servomotor

Code	[Basic type]
GYS	Slim type (Ultra-low inertia)
GYC	Cubic type (Low inertia)
GYG	Middle inertia type
Code	[Rated output]
500	50×10°=0.05kW
101	10×10¹=0.1kW
201	20×10 ¹ =0.2kW
401	40×10 ¹ =0.4kW, 0.375kW
501	50×10 ¹ =0.5kW
751	75×10 ¹ =0.75kW
851	85×10 ¹ =0.85kW
102	10×10 ² =1.0kW
132	13×10 ² =1.3kW
152	15×10 ² =1.5kW
202	20×10 ² =2.0kW
302	30×10 ² =3.0kW
402	40×10 ² =4.0kW
502	50×10 ² =5.0kW
Code	[Rated speed]
D	3000r/min series
С	2000r/min series
В	1500r/min series

5

5

\dashv	Code	[Brake]				
	Blank	Not provided				
	В	Provided				

Code	[Input voltage]
2	3-phase 200 VAC
6	Single-phase 100 VAC

Code	[Oil seal/shaft]	GYS, GYC, GYG
А	Without an oil seal, straight shaft with a key	△ (*○)
В	Without an oil seal, straight shaft without a key	0
С	Without an oil seal, straight shaft with a key, tapped	0
Е	With an oil seal, straight shaft with a key	Δ
F	With an oil seal, straight shaft without a key	Δ
G	With an oil seal, straight shaft with a key, tapped	Δ

- O: Standard item O: Semi-standard item
- △: Made-to-order item
 * Applicable with GYS and GYC motors of 0.1kW or less

_	Code	[Encoder]
	Η	18-bit ABS/INC
	R	20-bit INC

Common specifications

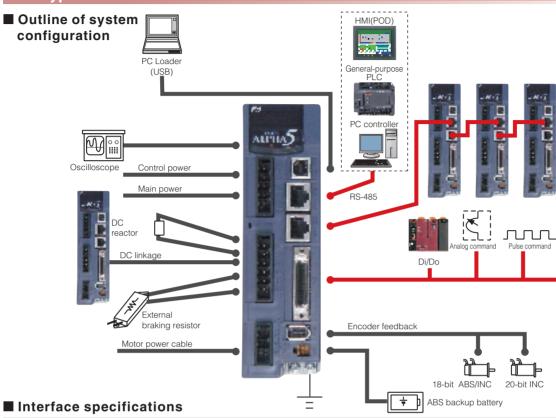
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							0.1	0.2	0.4				20 30	4.0	5.0	0.5		_		20					
CG-6-0-02									_	0.0	0.70		1.0		0.0	0.00	1.0								
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More labely evaluation More labely evaluat	Š	Control power					2/00/1																		
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Note Position Po			Allowable voltage fluctuation												F	C170 to	262V								
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Septicularian Speed fluctuation Speed fluctuation Power supply fluctuation 10 to 100% Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 0 to 100%) Within ± 1 f/min (load fluctuation 1 to 1 + 10%) Within ± 1 f/min (load fluctuation 1 to 1			External resistor *1			25	25	17	17	17	17	50	50	50	260 260	300	300	50	50 5	50	260	260	50	50	260
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Power supply fluctuation Within ±0.2% (25 ±10°C at rated operation speed and analog input operation)	Ove	erload capabili	·																						
Position function Within ± 1 /min (power supply fluctuation −10 to +10%) Temperature fluctuation Temperature fluc	Sne	ed fluctuation																							
Vitype Speed control function Within ±10.2% (26.±10.0° cal rated operation speed and analog input operation mesetting, manual feed rate/max. rotation speed, speed command zero clamp, etc. Witype Speed control function Winher of position data sets 15-point (position, speed, acceleration/deceleration time setting, timer, M code and various statuses) Torque control function Closed loop control with speed adjuster, acceleration/deceleration time setting, timer, M code and various statuses) Closed loop control with current adjuster (proportional open loop control of current and torque), torque limit, speed limit at torque control, etc. Accessory functions Accessory functions Accessory functions Closed loop control with speed adjuster, acceleration/deceleration time setting, manual feed rate/max. rotation speed, etc. Position control function Closed loop control with speed adjuster, acceleration/deceleration time setting, developed in the speed limit at torque control, etc. Accessory functions Accessory functions Closed loop control with speed adjuster, acceleration/deceleration time setting, fixed forward, homing, interrupt positioning, atc. Closed loop control with speed adjuster, acceleration/deceleration time setting, fixed and torque), torque limit, speed limit at torque control, etc. Accessory functions Accessory functions Closed loop control with speed adjuster, acceleration/deceleration time setting, developed in control function Closed loop control with the current adjuster, electronic gear, output pulse setting, flend forward, homing, interrupt positioning, etc. Closed loop control with speed adjuster, acceleration/deceleration time setting, timent and torque), torque limit, speed limit at torque control, etc. Accessory functions Accessor	•		Power supply fluctuation			- "																			
VV type Position control function Closed loop control with position adjuster, electronic gear, output pulse setting, feed forward, horning, interrupt positioning, auto startup, etc.	Tatio	,	Temperature fluctuation	Withir	1 ±0.2	% (25	±10°C	at rat	ed ope	eration s	speed	and a	nalog	input (operation)										
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Torque control function Accessory functions VS type VS type VS type LS			Number of position data sets																						
Speed control function Speed control function Closed loop control with speed adjuster, acceleration/deceleration time setting, manual feed rate/max. rotation speed, etc.		VV type	Positon control function	Close																					
LS type Max positioning value ±2,000,000,000 Positioning method Absolute / incremental Accessory functions Easy tuning, profile operation, sequence test mode, auto tuning, auto notch filter, vibration suppressing online learning, etc. Covercurrent(cot., oc.2), Overspeed(oS), Control power undervoltage(Lvc), Overvoltage(Hv), Encoder trouble(Et1, Et2), Circuit trouble(ct), Memory Error(dE), Fuse Broken(Fb), Motor Combination Error(cE), Braking transistor overheat(tH), Encoder Communication error(Ec), CONT(Control signal) Error(ctE), Overload(oL1, oL2), Main power undervoltage(Lvc), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(AH), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF)	드		Torque control function	Close																					
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Positioning method Absolute / incremental	Ca		Number of position data sets	99-point (position, speed, timer, M code and various statuses)																					
Protective function		LS type	Max positioning value	±2,00	00,000	,000																			
Protective function (Alarm indication) Poperation and display section of main body (keypad) Working conditions Installation place Incape and the place conditions			Positioning method	Abso	lute / ir	ncrem	ental																		
Memory Error(dE), Fuse Broken(Fb), Motor Combination Error(cE), Braking transistor overheat(tH), Encoder Communication error(Ec), CONT(Control signal) Error(ctE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(AH), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF) 6-digit alphanumeric display with 7-segment LED 4 operation switches Analog monitor connector (CN6), status indication LED Indoors (free from direct sunshine), altitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust In case of compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity -10 to 55°C/10 to 90%RH (without condensation) Vibration / shock resistance 4.9m/s²/19.6m/s²			Accessory functions	Easy	tuning	, profi	le oper	ation,	seque	nce test	mode	, auto	tuning	g, auto	notch filter	, vibrati	on sup	pressir	ng online	lear	ning, e	etc.			
CONT(Control signal) Error(ctE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(AH), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF) Operation and display section of main body (keypad) Operation and display section of main body (keypad) Installation place Include (CN6), status indication LED Indoors (free from direct sunshine), altitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust In case of compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity Vibration / shock resistance 4.9m/s²/19.6m/s² CONT(Control signal) Error(ctE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(FH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF) 6-digit alphanumeric display with 7-segment LED 4 operation switches 4 ope				Overd	current	(oc1,	oc2), C	versp	eed(o	S), Conti	rol pov	wer ur	ndervo	ltage(l	Lvc), Overv	oltage(l	Hv), En	coder	trouble(E	t1, E	Et2), Ci	ircuit tr	ouble(ct),	
CONT(Control signal) Error(ctE), Overload(oL1, oL2), Main power undervoltage(LvP), Braking resistor overheat(rH1, rH2, rH3), Deviation overflow(oF), Amplifier overheat(AH), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF) 6-digit alphanumeric display with 7-segment LED 4 operation switches Analog monitor connector (CN6), status indication LED Indoors (free from direct sunshine), allitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust In case of compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity -10 to 55°C/10 to 90%RH (without condensation) 4.9m/s²/19.6m/s² 4.9m/s²/19.6m/s²	Dro	taativa funatia		Memo	ory Err	or(dE	, Fuse	Broker	n(Fb),	Motor C	ombin	ation	Error(E), Br	aking trans	istor ov	erheat(tH), Er	coder C	omm	nunicat	ion en	or(Ec)	,	
Deviation overflow(oF), Amplifier overfleat(AH), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Command pulse Frequency Error(HF) Operation and display section of main body (keypad) Working conditions Installation place Incorp in the compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity -10 to 55°C/10 to 90%RH (without condensation) Vibration / shock resistance 4.9m/s²/19.6m/s² Deviation overflow(oF), Amplifier overflow(AF), Encoder overheat(EH), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Absolute data Lost(dL1, dL2, dL3), Multi-turn data over flow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Absolute data Lost(dL1, dL2, dL3), Multi-turn data overflow(AF), Initial Error(iE), Amplifier overflow(AF), Initial Error(iE), Initi				CON	T(Cont	rol sig	nal) Er	ror(ctE), Ove	rload(oL	_1, oL:	2), Ma	in pov	er und	dervoltage(_vP), Bı	aking i	esisto	overhea	t(rH	1, rH2,	rH3),			
Operation and display section of main body (keypad) Conditions Famperature/humidity Vibration / shock resistance 6-digit alphanumeric display with 7-segment LED 4 operation switches Analog monitor connector (CN6), status indication LED Indoors (free from direct sunshine), altitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust In case of compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III - 10 to 55°C/10 to 90%RH (without condensation) 4.9m/s²/19.6m/s² - 4.9m/s²/19.6m/s²	(Ala	iriii iiidication	1	Devia	ation ov	erflov	v(oF), A	mplifie	er over	heat(AF	H), End	coder	overh	eat(EH	l), Absolute	data Lo	st(dL1	, dL2,	dL3), Mu	lti-tu	ırn data	a over	flow(A	F),	
Operation and display section of main body (keypad) 4 operation switches A nalog monitor connector (CN6), status indication LED Indoors (free from direct sunshine), allitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust In case of compliance with CE marking Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity (Vibration / shock resistance (Vibration / shock resistance) -10 to 55°C/10 to 90%RH (without condensation)				Initial	Error(i	E), C	omman	d puls	e Freq	uency E	rror(H	IF)													
A operation switches	_			6-dig	it alpha	anum	eric dis	play w	ith 7-s	egment	LED														
Working conditions Installation place Indoors (free from direct sunshine), altitude ≤ 1000m, free from corrosive and flammable gases, oil mist and dust	-		section of main body	4 ope	eration	switc	nes																		
Working conditions In stallation place conditions place in case of compliance with CE marking in Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity libration / shock resistance in Vibration / shock resistance	(key	oad)		Analo	g mon	itor c	onnecto	or (CN	6), stat	us indic	ation	LED													
Working conditions In stallation place conditions place in case of compliance with CE marking in Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity libration / shock resistance in Vibration / shock resistance					-								ee fron	corro	sive and fla	ımmabl	e gase	s, oil m	nist and c	ust					
Working conditions Models compliant with EU directive: pollution degree 2, over voltage category III Temperature/humidity -10 to 55°C/10 to 90%RH (without condensation) Vibration / shock resistance 4.9m/s²/19.6m/s²	144	alain n	Installation place																						
Temperature/humidity -10 to 55°C/10 to 90%RH (without condensation) Vibration / shock resistance 4.9m/s²/19.6m/s² 4.9m/s²/19.6m/s²		•	-							0	degre	ee 2, c	over vo	ltage	category II										
Vibration / shock resistance 4.9m/s²/19.6m/s²	con	aitions	Temperature/humidity												<u> </u>										
								, ,,,,																	
	Star	ndards				_	, CE m	arkina	(low v	oltage d	directiv	re EN6	61800-	5-1) (2	acquisition	oeina a	pplied	for mo	del of 2.0	kW (or more	e), Ro	HS dire	ective	

^{*1:} The figure is data determined when the amplifier is connected with an external resistor dedicated for each model.

^{*2:} We will accept custom orders for models without dynamic brake.



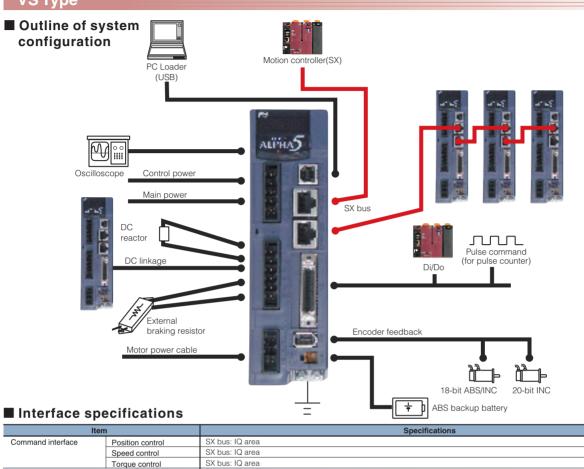
VV Type



Iten	1	Specifications
Command interface	Positioning function	RS-485 (Modbus-RTU), Di/Do
	Position control	Pulse input
	Speed control	Analog voltage input
	Torque control	Analog voltage input
Communication interface		Two RS-485 ports (for parameter editing and monitor)
		Our original protocol Modbus-RTU
		9600/19200/38400 bps, connection of max. 31 axes

Terminal name	Symbol	Specifications
Pulse input	CA,*CA	Pulse input under position control
	CB,*CB	Differential input: max. input frequency ≤ 1.0MHz
		Open collector input: max. input frequency ≤ 200kHz
		(in case of signals at 90-degree phase difference, the above relationship is true for the four-fold frequency.)
		Pulse format Command pulse/Command direction)
		Forward/Reverse pulse Select one of these formats with a parameter setting.
		Two signals at 90-degree phase difference)
	PPI	Pull-up power input at open collector input
		(24VDC ±10%)
Pulse output	FFA,*FFA	Differential output: max. output frequency ≤ 1MHz
	FFB,*FFB	Two signals at 90-degree phase difference
		Pulse output count setting n pulses/rev): 16 ≤ n ≤ 262144
	FFZ,*FFZ	Differential output: 1 pulse/rev
	FZ	Open collector output: 1 pulse/rev
	M5	Reference potential (0V)
Analog monitor	MON1	0V to ±10VDC
voltage output	MON2	Resolution: 14bits / ±full scale
		The output data depends on internal parameter.
	M5	Reference potential (0V)
Common for sequence	COMIN	Common for sequence input signal
I/O	COMOUT	Common for sequence output signal
Sequence input signal	CONT1 to CONT8	ON upon short circuit across contacts, OFF upon open circuit
		12VDC-10% to 24VDC+10%
		Current consumption 20mA (per contact; used at 24VDC circuit voltage)
		Function of each signal depends on parameter setting
		Compatible with both sink and source input methods
Sequence output signal	OUT1 to OUT5	Short circuit upon ON, open circuit upon OFF
		30VDC / 50mA (max.)
		Function of each signal depends on parameter setting
		Compatible with both sink and source output methods
Analog voltage input	VREF	Speed command input for speed control
		Input range: from -10 to 0 to -10V, input impedance 20kΩ
		Resolution: 15 bits / ±full scale
	TREF	Torque command input for torque control
		Input range: from -10 to 0 to +10V, input impedance 20kΩ
		Resolution: 14 bits / ±full scale
	P10	Power supply output for analog command (+10 VDC), output capacity 30 mA
	M5	Reference potential (0V)

VS Type

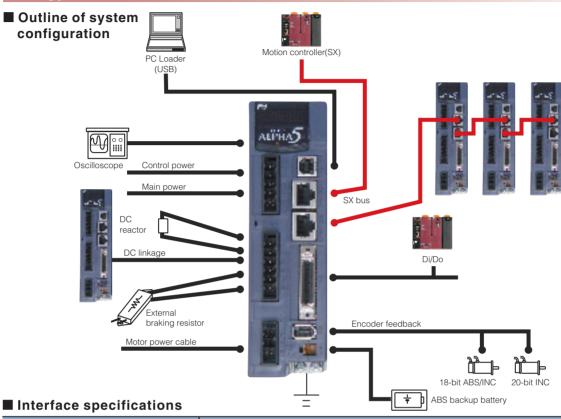


It	em	Specifications
Command interface Position control		SX bus: IQ area
	Speed control	SX bus: IQ area
	Torque control	SX bus: IQ area
Communication interface		SX bus (for command interface, parameter editing and monitor)
		Our original protocol
		25Mbps_connection of may 32 axes

		ZUMIDPS, COMMECTION OF MAX. 92 AXES					
Terminal name	Symbol	Specifications					
Pulse input	CA,*CA CB,*CB	Pulse input during operation with high speed counter function Differential input: max. input frequency ≤ 1.0MHz Open collector input: max. input frequency ≤ 200kHz					
		(In case of signals at 90-degree phase difference, the above relationship is true for the four-fold frequency.) Pulse format Command pulse/Command direction Forward/Reverse pulse Select one of these formats with a parameter setting.					
		Two signals at 90-degree phase difference					
	PPI	Pull-up power input at open collector input (24VDC ± 10%)					
Pulse output	FFA,*FFA	Differential output: max. output frequency ≤ 1MHz					
	FFB,*FFB	Two signals at 90-degree phase difference Pulse output count setting (n pulses/rev): 16 ≤ n ≤ 262144					
	FFZ,*FFZ	Differential output 1 pulse/rev					
	FZ	Open collector output 1 pulse/rev					
	M5	Reference potential (0V)					
Analog monitor	MON1	0V to ± 10VDC					
voltage output	MON2	Resolution: 14 bits / ±full scale					
		The output data depends on the internal parameter.					
	M5	Reference potential (0V)					
Common for sequence	COMIN	Common for sequence input signal					
I/O	COMOUT	Common for sequence output signal					
Sequence input signal	CONT1 to CONT5	ON upon short circuit across contacts, OFF upon open circuit					
		12VDC-10% to 24VDC +10%					
		Current consumption 20mA (per contact; use at circuit voltage 24 VDC)					
		Function of each signal depends on parameter setting					
		Compatible with both sink and source input methods					
Sequence output signal	OUT1 to OUT2	Short circuit upon ON, open circuit upon OFF					
		30VDC / 50mA (max.)					
		Function of each signal depends on parameter setting					
		Compatible with both sink and source output methods					



LS Type

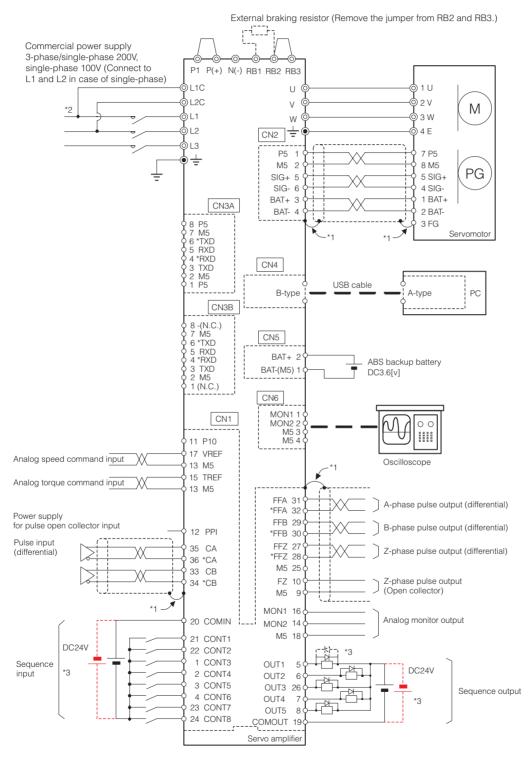


Ite	em	Specifications
Command interface Positioning Function		SX bus: IQ area
	Position control	SX bus: IQ area
	Speed control	SX bus: IQ area
Communication interface		SX bus (for command interface, parameter editing and monitor)
		Our original protocol
		25Mbps, connection of max, 32 axes

		25Mbps, connection of max. 32 axes						
Terminal name	Symbol	Specifications						
Pulse input	CA,*CA	Pulse train command input for position control						
	CB,*CB	Differential input: max. input frequency ≤ 1.0MHz						
		Open collector input: max. input frequency ≤ 200kHz						
		(In case of signals at 90-degree phase difference, the above relationship is true for the four-fold frequency.)						
		Pulse format Command pulse/Command direction						
		Forward/Reverse pulse Select one of these formats with a parameter setting.						
		Two signals at 90-degree phase difference)						
	PPI Pull-up power input at open collector input							
		(24VDC ± 10%)						
Pulse output	FFA,*FFA	Differential output: max. output frequency ≤ 1MHz						
	FFB,*FFB	Two signals at 90-degree phase difference						
		Pulse output count setting (n pulses/rev): 16 ≤ n ≤ 262144						
	FFZ,*FFZ	Differential output 1 pulse/rev						
	FZ	Open collector output 1 pulse/rev						
	M5	Reference potential (0V)						
Analog monitor	MON1	0V to ± 10VDC						
voltage output	MON2	Resolution: 14 bits / ±full scale						
		The output data depends on the internal parameter.						
	M5	Reference potential (0V)						
Common for sequence	COMIN	Common for sequence input signal						
1/0	COMOUT	Common for sequence output signal						
Sequence input signal	CONT1 to CONT5	ON upon short circuit across contacts, OFF upon open circuit						
		12VDC-10% to 24VDC +10%						
		Current consumption 20mA (per contact; use at circuit voltage 24 VDC)						
		Function of each signal depends on parameter setting						
		Compatible with both sink and source input methods						
Sequence output signal	OUT1 to OUT2	Short circuit upon ON, open circuit upon OFF						
		30VDC / 50mA (max.)						
		Function of each signal depends on parameter setting						
		Compatible with both sink and source output methods						

Connection Diagram (Reference)

VV type



- *1: Connect the shield to the connector shell of CN1 and CN2. The connector shell is at the ground potential (FG).
- *2: Supply the control power (L1c and L2c) without fail. (The servo amplifier does not function with merely the main power supply.)
- *3: To use in the source I/O, connect as shown with the broken line. Connect the surge absorber diode of the output load with the reverse polarity.



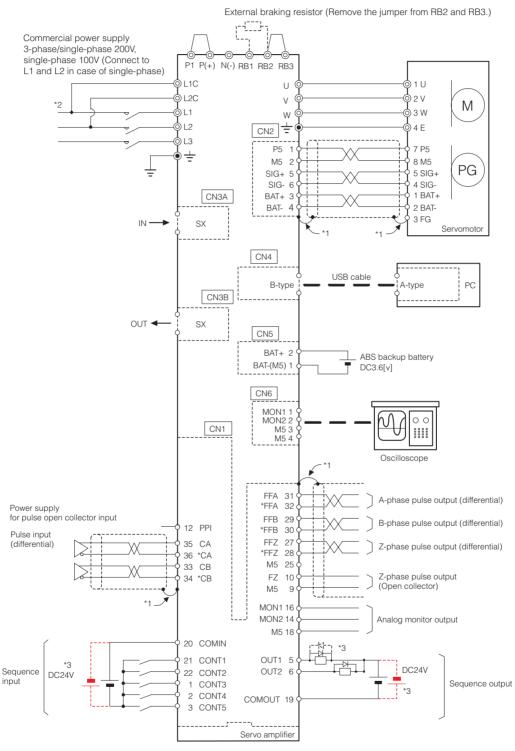
The diagram shown above is given as a reference for model selection.

When actually using the selected servo system, make wiring connections according to the connection diagram and instructions described in the user's manual.



Connection Diagram (Reference)

VS type, LS type



- *1: Connect the shield to the connector shell of CN1 and CN2. The connector shell is at the ground potential (FG).
- *2: Supply the control power (L1c and L2c) without fail. (The servo amplifier does not function with merely the main power supply.)
- *3: To use in the source I/O, connect as shown with the broken line. Connect the surge absorber diode of the output load with the reverse polarity.



The diagram shown above is given as a reference for model selection. When actually using the selected servo system, make wiring connections according to the connection diagram and instructions described in the user's manual.

GYS Motor

200V series

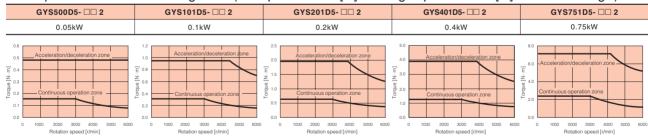
■Standard specifications

Motor type (-B) indicates the brake-inco	orporated type.	GYS500D5 - □□ 2 (-B)	GYS101D5 - □□ 2 (-B)	GYS201D5 - □□ 2 (-B)	GYS401D5 - □□ 2 (-B)	GYS751D5 - □□ 2 (-B)			
Rated output	[kW]	0.05	0.1	0.2	0.4	0.75			
Rated torque	[N · m]	0.159	0.318	0.637	1.27	2.39			
Rated speed	[r/min]	3000			•				
Max. speed	[r/min]	6000*1							
Max. torque	[N · m]	0.478	0.955	1.91	3.82	7.17			
Inertia	[kg · m²]	0.0192×10 ⁻⁴	0.0371×10 ⁻⁴	0.135×10 ⁻⁴	0.246×10 ⁻⁴	0.853×10 ⁻⁴			
() indicates brake-inco	orporated type.	(0.0223×10 ⁻⁴)	(0.0402×10 ⁻⁴)	(0.159×10 ⁻⁴)	(0.270×10 ⁻⁴)	(0.949×10 ⁻⁴)			
Recommended load ine	rtia ratio	30 times or less*2							
Rated current	[A]	0.85	0.85	1.5	2.7	4.8			
Max. current	[A]	2.55	2.55	4.5	8.1	14.4			
Winding insulation class	3	Class B							
Operation duty type		Continuous							
Degree of enclosure pro	otection	Totally enclosed, self-cooled	d (IP 67. excluding the shaft s	ealing and connectors)					
Terminals (motor)		Cable 0.3m (with connector))						
Terminals (encoder)		Cable 0.3m (with connector)							
Overheat protection		Not provided (The servo am	plifier detects temperature.)						
Mounting method		By securing motor flange IMB5 (L51), IMV1 (L52), IMV3 (L53)							
Shaft extension		Straight shaft							
Paint color		N1.5							
Encoder		18-bit serial encoder (absolu	ute/incremental), 20-bit serial	encoder (incremental)					
Vibration level		V5 or below							
Installation place, altitude a	and environment	For indoor use (free from dir	ect sunlight), 1000m or below	, locations without corrosive a	and flamable gases, oil mist ar	nd dust			
Ambient temperature, h	umidity	-10 to +40°C, within 90% RH	I max.(without condensation)						
Vibration resistance	[m/s ²]	49							
Mass	[kg]	0.45	0.55	1.2	1.8	3.4			
() indicates brake-inco	orporated type.	(0.62)	(0.72)	(1.7)	(2.3)	(4.2)			
Compliance with standa	ırds	UL/cUL (UL1004), CE markii	ng (EN60034-1, EN60034-5),	RoHS directive					

■Brake specification (motor equipped with a brake)

		(a a			
Motor type		GYS500D5 - □□ 2-B	GYS101D5 - □□ 2-B	GYS201D5 - □□ 2-B	GYS401D5 - □□ 2-B	GYS751D5 - □□ 2-B
Static friction torque	[N · m]	0.0	34	1.2	2.45	
Rated DC voltage	[V]	DC24±10%				
Attraction time	[ms]	3	5	4	60	
Release time	[ms]	1	10		20	
Power consumption	[W]	6.1 (at	20°C)	7.3 (at	8.5 (at 20°C)	

■Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier. The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

Model GYS500, 101: $200 \times 200 \times 6$ [mm]

Model GYS201, 401: 250 × 250 × 6 [mm]

· Model GYS751: 300 × 300 × 6 [mm]

^{*1} The maximum rotation speed is 5000r/min when using the motor in combination with Fuji's gear head.
*2 The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.



GYS Motor

200V series

■Standard specifications

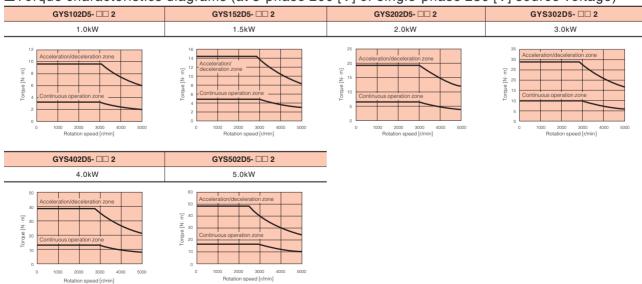
Motor type (-B) indicates the brake-incorporated type.	GYS102D5 - □□ 2 (-B)	GYS152D5 - □□ 2 (-B)	GYS202D5 - □□ 2 (-B)	GYS302D5 - □□ 2 (-B)	GYS402D5 - □□ 2 (-B)	GYS502D5 - □□ 2 (-B)			
Rated output [kW]	1.0	1.5	2.0	3.0	4.0	5.0			
Rated torque [N · m]	3.18	4.78	6.37	9.55	12.7	15.9			
Rated speed [r/min]	3000								
Max. speed [r/min]	5000								
Max. torque [N · m]	9.55	14.3	19.1	28.7	38.2	47.8			
Inertia [kg · m ²]	1.73×10 ⁻⁴	2.37×10 ⁻⁴	3.01×10 ⁻⁴	8.32×10 ⁻⁴	10.8×10 ⁻⁴	12.8×10 ⁻⁴			
() indicates brake-incorporated type.	(2.03×10 ⁻⁴)	(2.67×10 ⁻⁴)	(3.31×10 ⁻⁴)	(10.42×10 ⁻⁴)	(12.9×10 ⁻⁴)	(14.9×10 ⁻⁴)			
Recommended load inertia ratio	20 times or less*1								
Rated current [A]	7.1	9.6	12.6	18.0	24.0	30.0			
Max. current [A]	21.3	28.8	37.8	54.0	72.0	90.0			
Winding insulation class	Class F								
Operation duty type Continuous									
Degree of enclosure protection	Totally enclosed, self-c	otally enclosed, self-cooled (IP 67. excluding the shaft sealing)*2							
Terminals (motor)	erminals (motor) Cannon connector								
Terminals (encoder)	Cannon connector								
Overheat protection	Not provided (The serve	amplifier detects tempe	erature.)						
Mounting method	By securing motor flang	ge IMB5 (L51), IMV1 (L52	2), IMV3 (L53)						
Shaft extension	Straight shaft								
Paint color	N1.5								
Encoder	18-bit serial encoder (a	bsolute/incremental), 20-	-bit serial encoder (incre	mental)					
Vibration level	Up to rated rotation spe	ed: V10 or below							
	Over rated rotation spe	ed and up to 5000r/min:	V15 or below						
Installation place, altitude and environment	For indoor use (free from	n direct sunlight), 1000n	or below, locations with	out corrosive and flamat	ole gases, oil mist and di	ust			
Ambient temperature, humidity	-10 to +40°C, within 90°	% RH max.(without cond	ensation)						
Vibration resistance [m/s ²]	24.5								
Mass [kg]	4.4	5.2	6.3	11.0	13.5	16.0			
() indicates brake-incorporated type.	(5.9) (6.8) (7.9) (13.0) (15.5) (18.0)								
Compliance with standards	UL/cUL (UL1004), CE r	narking (EN60034-1, EN	60034-5), RoHS directive						

^{*1} The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.
*2 If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.

■Brake specification (motor equipped with a brake)

		·		,					
Motor type		GYS102D5 - □□ 2-B	GYS152D5 - □□ 2-B	GYS202D5 - □□ 2-B	GYS302D5 GYS402D5 GYS502D5 -				
Static friction torque	[N · m]		6.86			17			
Rated DC voltage	[V]	DC24±10%							
Attraction time	[ms]		100		120				
Release time	[ms]	ns] 40 30							
Power consumption	[W]	17.7 (at 20°C) 12 (at 20°C)							

■Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier. The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

· Model GYS102, 152, 202: 350 × 350 × 8 [mm]

· Model GYS302, 402, 502: 400 × 400 × 12 [mm]

GYS Motor

100V series

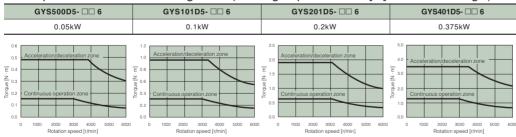
■Standard specifications

Motor type (-B) indicates the brake-incorpo	orated type.	GYS500D5 - □□ 6 (-B)	GYS101D5 - □□ 6 (-B)	GYS201D5 - □□ 6 (-B)	GYS401D5 - □□ 6 (-B)				
Rated output [kW]		0.05	0.1	0.2	0.375				
Rated torque [N · m]		0.159 0.318 0.637 1.1							
Rated speed	[r/min]	3000							
Max. speed	[r/min]	6000*1							
Max. torque	[N · m]	0.478	0.955	1.91	3.58				
Inertia	[kg · m²]	0.0192×10 ⁻⁴	0.0371×10 ⁻⁴	0.135×10 ⁻⁴	0.246×10 ⁻⁴				
() indicates brake-incorpo	rated type.	(0.0223×10 ⁻⁴)	(0.0402×10 ⁻⁴)	(0.159×10 ⁻⁴)	(0.270×10 ⁻⁴)				
Recommended load inertia	ratio	30 times or less*2							
Rated current	[A]	0.85	1.5	2.7	4.8				
Max. current	[A]	2.55	4.5	8.1	14.4				
Winding insulation class		Class B							
Operation duty type		Continuous							
Degree of enclosure protect	tion	Totally enclosed, self-cooled (IP 67. excluding the shaft sealing and connectors)							
Terminals (motor)		Cable 0.3m (with connector)							
Terminals (encoder)		Cable 0.3m (with connector)							
Overheat protection		Not provided (The servo amplifier detects temperature.)							
Mounting method		By securing motor flange IMB5 (L51), IMV1 (L52), IMV3 (L53)							
Shaft extension		Straight shaft							
Paint color		N1.5							
Encoder		18-bit serial encoder (absolute/incremental), 20-bit serial encoder (incremental)							
Vibration level		V5 or below							
Installation place, altitude and	environment	For indoor use (free from direct sunlight), 1000m or below, locations without corrosive and flamable gases, oil mist and dust							
Ambient temperature, hum	idity	-10 to +40°C, within 90% RH max.(without condensation)							
Vibration resistance	[m/s ²]	49							
Mass	[kg]	0.45	0.55	1.2	1.8				
() indicates brake-incorpo	orated type.	(0.6) (0.7) (1.7) (2.3)							
Compliance with standards	;	UL/cUL (UL1004), CE marking (EN6	0034-1, EN60034-5), RoHS directive		·				

■Brake specification (motor equipped with a brake)

Motor type		GYS500D5 - □□ 6-B	GYS101D5 - □□ 6-B	GYS201D5 - □□ 6-B	GYS401D5 - □□ 6-B			
Static friction torque	[N · m]	0.0	34	1.27				
Rated DC voltage	[V]	DC24±10%	DC24±10%					
Attraction time	[ms]	3	5	40				
Release time	[ms]	1	0	20				
Power consumption	[W]	6.1 (at	20°C)	7.3 (at 20°C)				

■Torque characteristics diagrams (at single-phase 100 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier. The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

- Model GYS500, 101: 200 \times 200 \times 6 [mm]
- Model GYS201, 401: 250 \times 250 \times 6 [mm]

^{*1} The maximum rotation speed is 5000r/min when using the motor in combination with Fuji's gear head.
*2 The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.



GYC Motor

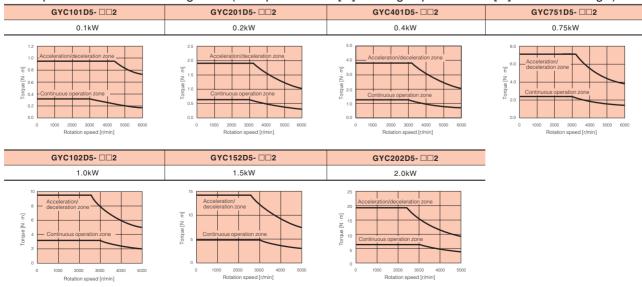
■Standard specifications

Motor type (-B) indicates the brake-incorporated type.	GYC101D5 - □□ 2 (-B)	GYC201D5 - □□ 2 (-B)	GYC401D5 - □□ 2 (-B)	GYC751D5 - □□ 2 (-B)	GYC102D5 - □□ 2 (-B)	GYC152D5 - □□ 2 (-B)	GYC202D5 - □□ 2 (-B)	
Rated output [kW]	0.1	0.2	0.4	0.75	1.0	1.5	2.0	
Rated torque [N · m]	0.318	0.637	1.27	2.39	3.18	4.78	6.37	
Rated speed [r/min]	3000							
Max. speed [r/min]		600	OO* ¹		5000			
Max. torque [N · m]	0.955	1.91	3.82	7.17	9.55	14.3	19.1	
Inertia [kg · m ²]	0.0577×10 ⁻⁴	0.213×10 ⁻⁴	0.408×10 ⁻⁴	1.21×10 ⁻⁴	3.19×10 ⁻⁴	4.44×10 ⁻⁴	5.69×10 ⁻⁴	
() indicates brake-incorporated type.	(0.0727×10 ⁻⁴)	(0.288×10 ⁻⁴)	(0.483×10 ⁻⁴)	(1.66×10 ⁻⁴)	(5.29×10 ⁻⁴)	(6.54×10 ⁻⁴)	(7.79×10 ⁻⁴)	
Recommended load inertia ratio		30 times	or less*2			20 times or less*2		
Rated current [A]	1.0	1.5	2.6	4.8	6.7	9.6	12.6	
Max. current [A]	3.0	4.5	7.8	14.4	20.1	28.8	37.8	
Winding insulation class		Cla	ss B	Class F				
Operation duty type	Continuous	ntinuous						
Degree of enclosure protection	Totally enclosed, s	elf-cooled (IP 67. exc	luding the shaft seali	Totally enclosed, self	-cooled (IP 67. excludi	ng the shaft sealing)*3		
Terminals (motor)		Cable 0.3m (v	vith connector)			Cannon connector		
Terminals (encoder)		Cable 0.3m (v	vith connector)		Cannon connector			
Overheat protection	Not provided (The s	ervo amplifier detect	s temperature.)					
Mounting method	By securing motor fl	lange IMB5 (L51), IM	V1 (L52), IMV3 (L53)					
Shaft extension	Straight shaft							
Paint color	N1.5							
Encoder	18-bit serial encode	r (absolute/incremen	tal), 20-bit serial enco	der (incremental)				
Vibration level		V5 or	below		Up to rate	ed rotation speed: V1	0 or below	
					Over rated rotation	speed and up to 500	0r/min: V15 or below	
Installation place, altitude and environment	For indoor use (free	from direct sunlight),	1000m or below, loc	ations without corros	ive and flamable gas	es, oil mist and dust		
Ambient temperature, humidity	-10 to +40°C, within	90% RH max.(withou	ut condensation)					
Vibration resistance [m/s²]		49				24.5		
Mass [kg]	0.75	1.3	1.9	3.5	5.7	7.0	8.2	
() indicates brake-incorporated type.	(1.0)	(1.9)	(2.6)	(4.3)	(8.0)	(9.8)	(11.0)	
Compliance with standards	UL/cUL (UL1004), C	E marking (EN60034	-1, EN60034-5), RoH	S directive	•		•	

■Brake specification (motor equipped with a brake)

Motor type		GYC101D5 - □□ 2-B	GYC201D5 - □□ 2-B	GYC401D5 - □□ 2-B	GYC751D5 - □□ 2-B	GYC102D5 - □□ 2-B	GYC152D5 - □□ 2-B	GYC202D5 - □□ 2-B
Static friction torque	[N · m]	0.318	1.	27	2.39	17		
Rated DC voltage	[V]	DC24±10%						
Attraction time	[ms]	60	8	0	50	120		
Release time	[ms]		40		80	30		
Power consumption	[W]	6.5 (at 20°C)	9.0 (at 20°C)		8.5 (at 20°C)	12 (at 20°C)		

■Torque characteristics diagrams (at 3-phase 200 [V] or single-phase 230 [V] source voltage)



These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier.

The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

- · Model GYC101, 201, 401: 250 × 250 × 6 [mm]
- · Model GYC751: 300 × 300 × 6 [mm]
- · Model GYC102D: 300 × 300 × 12 [mm]
- · Model GYC152D, 202D: 400 \times 400 \times 12 [mm]

^{*1} The maximum rotation speed is 5000r/min when using the motor in combination with Fuji's gear head.
*2 The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.
*3 If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.

GYG Motor [2000r/min]

■Standard specifications

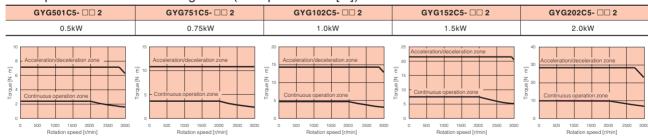
Motor type (-B) indicates the brake-incorporated type.	GYG501C5 - □□ 2 (-B)	GYG751C5 - □□ 2 (-B)	GYG102C5 - □□ 2 (-B)	GYG152C5 - □□ 2 (-B)	GYG202C5 - □□ 2 (-B)				
Rated output [kW]	0.5	0.75	1.0	1.5	2.0				
Rated torque [N · m]	2.39	3.58	4.77	7.16	9.55				
Rated speed [r/min]	2000	oo							
Max. speed [r/min]	3000								
Max. torque [N · m]	7.2	10.7	14.3	21.5	28.6				
Inertia [kg · m ²]	7.96×10 ⁻⁴	11.55×10 ⁻⁴	15.14×10 ⁻⁴	22.33×10 ⁻⁴	29.51×10 ⁻⁴				
() indicates brake-incorporated type.	(10.0×10 ⁻⁴)	(13.6×10 ⁻⁴)	(17.2×10 ⁻⁴)	(24.4×10 ⁻⁴)	(31.6×10 ⁻⁴)				
Recommended load inertia ratio	10 times or less*1								
Rated current [A]	3.5	5.2	6.4	10	12.3				
Max. current [A]	10.5	15.6	19.2	30.0	36.9				
Winding insulation class	Class F	Class F							
Operation duty type	Continuous								
Degree of enclosure protection	Totally enclosed, self-cooled (IP 67. excluding the shaft sealing)*2								
Terminals (motor)	Cannon connector								
Terminals (encoder)	Cannon connector								
Overheat protection	Not provided (The servo am	olifier detects temperature.)							
Mounting method	By securing motor flange IM	B5 (L51), IMV1 (L52), IMV3 (L	.53)						
Shaft extension	Straight shaft								
Paint color	N1.5								
Encoder	18-bit serial encoder (absolu	ite/incremental), 20-bit serial	encoder (incremental)						
Vibration level	V10 or below								
Installation place, altitude and environment	For indoor use (free from dire	ect sunlight), 1000m or below	, locations without corrosive a	nd flamable gases, oil mist ar	nd dust				
Ambient temperature, humidity	-10 to +40°C, within 90% RH	max.(without condensation)							
Vibration resistance [m/s²]	24.5								
Mass [kg]	5.3	6.4	7.5	9.8	12.0				
() indicates brake-incorporated type.	(7.5) (8.6) (9.7) (12.0) (14.2)								
Compliance with standards	UL/cUL (UL1004), CE markir	ng (EN60034-1, EN60034-5),	RoHS directive						

^{*1} The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.

■Brake specification (motor equipped with a brake)

Motor type		GYG501C5 - □□ 2-B	GYG751C5 - □□ 2-B	GYG102C5 - □□ 2-B	GYG152C5 - □□ 2-B	GYG202C5 - □□ 2-B
Static friction torque	[N · m]	17				
Rated DC voltage	[V]	DC24±10%				
Attraction time	[ms]	120				
Release time	[ms]	30				
Power consumption	[W]	12 (at 20°C)				

■Torque characteristics diagrams (at 3-phase 200[V])



These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier.

The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

- Model GYG501C, 751C, 102C: 300 \times 300 \times 12 [mm]
- · Model GYG152, 202: 400 × 400 × 12 [mm]

^{*2} If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.



GYG Motor [1500r/min]

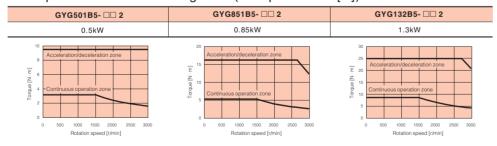
■Standard specifications

Motor type (-B) indicates the brake-incorporated type.	GYG501B5 - □□ 2 (-B)	GYG851B5 - □□ 2 (-B)	GYG132B5 - □□ 2 (-B)					
Rated output [kW]	0.5	0.85	1.3					
Rated torque [N · m]	3.18	5.41	8.28					
Rated speed [r/min]	1500							
Max. speed [r/min]	3000							
Max. torque $[N \cdot m]$	9.5	16.2	24.8					
Inertia [kg · m ²]	11.55×10 ⁻⁴	15.15×10 ⁻⁴	22.33×10 ⁻⁴					
() indicates brake-incorporated type	(13.6×10 ⁻⁴)	(17.3×10 ⁻⁴)	(24.5×10 ⁻⁴)					
Recommended load inertia ratio	10 times or less*1							
Rated current [A]	4.7	7.3	11.5					
Max. current [A]	14.1	34.5						
Winding insulation class Class F								
Operation duty type	Continuous							
Degree of enclosure protection	Totally enclosed, self-cooled (IP 67. excluding t	Totally enclosed, self-cooled (IP 67. excluding the shaft sealing)*2						
Terminals (motor)	Cannon connector							
Terminals (encoder)	Cannon connector							
Overheat protection	Not provided (The servo amplifier detects temperature)	erature.)						
Mounting method	By securing motor flange IMB5 (L51), IMV1 (L52	2), IMV3 (L53)						
Shaft extension	Straight shaft							
Paint color	N1.5							
Encoder	18-bit serial encoder (absolute/incremental), 20	-bit serial encoder (incremental)						
Vibration level	V10 or below							
Installation place, altitude and environment	For indoor use (free from direct sunlight), 1000n	n or below, locations without corrosive and flamab	ole gases, oil mist and dust					
Ambient temperature, humidity	-10 to +40°C, within 90% RH max.(without cond	ensation)						
Vibration resistance [m/s²]	24.5							
Mass [kg]	6.4	7.5	9.8					
() indicates brake-incorporated type	(8.6) (9.7) (12.0)							
Compliance with standards	UL/cUL (UL1004), CE marking (EN60034-1, EN	60034-5), RoHS directive						

■Brake specification (motor equipped with a brake)

Motor type		GYG501B5 - □□ 2-B	GYG851B5 - □□ 2-B	GYG132B5 - □□ 2-B
Static friction torque	[N · m]	17		
Rated DC voltage	[V]	DC24±10%		
Attraction time	[ms]	120		
Release time	[ms]	30		
Power consumption	[W]	12 (at 20°C)		

■Torque characteristics diagrams (at 3-phase 200[V])



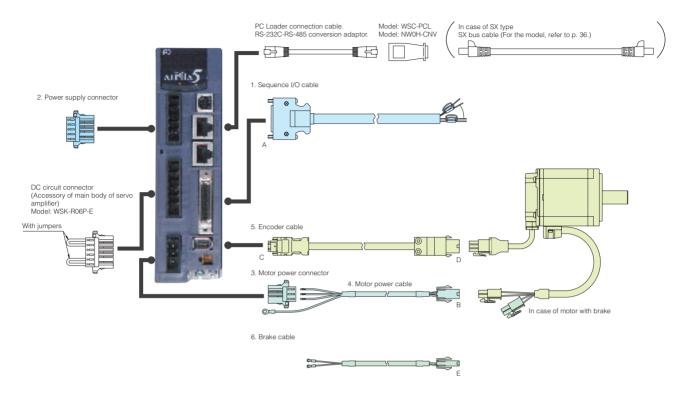
These characteristics indicate typical values of each servomotor combined with the corresponding RYT type servo amplifier. The rated torque indicates the value obtained when the servo amplifier is installed to the following aluminum heat sink.

- Model GYG501B, 851B: 300 × 300 × 12 [mm]
- · Model GYG132: 400 × 400 × 12 [mm]

^{*1} The load inertia ratio to the inertia of servo motor. If the moment of load inertia ratio value exceeds the list value, please contact us.
*2 If the motor is used in the environment rated to IP67 protection degree, use the wiring connector suitable for the protection degree.

Option/Peripheral Equipment

<Major example: 750W or less / 3000r/min>



Option

■Basic option

Motor series	Rated speed	Brake	Rated output	Sequence I/O cable (between host and amplifier)	2. Power supply connector			5. Encoder cable (between amplifier and motor)	6. Brake cable
GYS motor	3000r/min	Without brake With brake Without brake With brake	0.05kW to 0.75kW		WSK-S05P-E	WSK-M03P-E (Excluding 2kW)	WSC-M04P02-E WSC-M04P05-E WSC-M04P10-E WSC-M04P20-E *1	WSC-P06P02-E WSC-P06P05-E WSC-P06P10-E WSC-P06P20-E WSC-P06P05-C	WSC-M02P02-E WSC-M02P05-E WSC-M02P10-E WSC-M02P20-E
		Without brake	3.0kW to 5.0kW	1	_	_	*3	WSC-P06P10-C	_
		With brake			_	_	*4	WSC-P06P20-C	_
GYC motor	3000r/min	Without brake With brake	0.05kW to 0.75kW	WSC-D36P03	WSK-S05P-E	WSK-M03P-E (Excluding 2kW)	WSC-M04P02-E WSC-M04P05-E WSC-M04P10-E WSC-M04P20-E	WSC-P06P02-E WSC-P06P05-E WSC-P06P10-E WSC-P06P20-E	WSC-M02P02-E WSC-M02P05-E WSC-M02P10-E WSC-M02P20-E
		Without brake	1.0kW to 2.0kW	1		,	*3		_
		With brake					*4		*No cable is required.
GYG motor	2000r/min	Without brake	0.5kW to 1.0kW		WSK-S05P-E	WSK-M03P-E	*1		_
		With brake		_		WORKINGON E	*2	WSC-P06P05-C	*No cable is required.
		Without brake	1.5kW to 2.0kW			_	*1	WSC-P06P10-C	***************************************
	1500r/min	With brake Without brake	0.5kW to 0.85kW	4		_	*2	WSC-P06P20-C	*No cable is required.
	15001/111111	With brake	0.5kw to 0.65kw		WSK-S05P-E	WSK-M03P-E	*2		*No cable is required.
		Without brake	1.3kW	1	_	_	*1		—
		With brake			_	_	*2		*No cable is required.

^{*1} The customer is requested to fabricate the cable using the connector for motor power (motor without brake): WSK-M04P-CA.

^{*2} The customer is requested to fabricate the cable using the connector for motor power (motor with brake): WSK-M06P-CA.

^{*3} The customer is requested to fabricate the cable using the connector for motor power (motor without brake): WSK-M04P-CB.

^{*4} The customer is requested to fabricate the cable using the connector for motor power (motor with brake): WSK-M06P-CB.



Option/Peripheral Equipment

Option

■Connector kit * Use this connector if the customer fabricates the cable yourself.

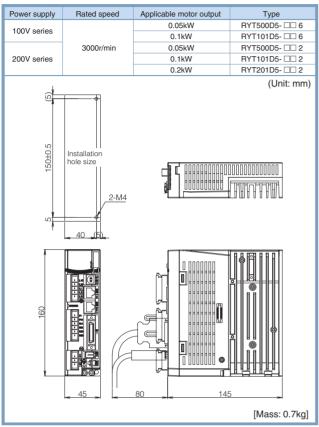
	Bata damand	Bt.	Bata di controla	A Sequence I/O	B Motor power connector	Encoder of	onnector	E B
Motor series	Rated speed	Brake	Rated output	connector	(on motor side)	C Amplifier side	D Motor side	E Brake connector
GYS motor	3000r/min	Without brake	0.05kW to 0.75kW		WSK-M04P-E		WSK-P09P-D	_
		With brake			WSK-WU4F-E		W5K-P09P-D	WSK-M02P-E
		Without brake	1.0kW to 1.5kW		WSK-M04P-CA			_
		With brake			WSK-M06P-CA			_
		Without brake	2.0kW		WSK-M04P-CA		WSK-P06P-C	_
		With brake			WSK-M06P-CA		WSN-PU6P-C	_
		Without brake	3.0kW to 5.0kW		WSK-M04P-CB			_
		With brake			WSK-M06P-CB			_
GYC motor	3000r/min	Without brake	0.05kW to 0.75kW		WSK-M04P-E		WSK-P09P-D	_
		With brake		WSK-D36P WSK-D36P	WSN-WU4F-E	WSK-P06P-M	VVOIC-1 031 -D	WSK-M02P-E
		Without brake	1.0kW to 1.5kW	WSN-DS0F	WSK-M04P-CB	WSK-FUOF-IVI		
		With brake			WSK-M06P-CB			
		Without brake	2.0kW		WSK-M04P-CB			
		With brake			WSK-M06P-CB			
GYG motor	2000r/min	Without brake	0.5kW to 1.0kW		WSK-M04P-CA			
		With brake			WSK-M06P-CA		WSK-P06P-C	
		Without brake	1.5kW to 2.0kW		WSK-M04P-CA		***************************************	
		With brake			WSK-M06P-CA			
	1500r/min	Without brake	0.5kW to 0.85kW		WSK-M04P-CA			
	1	With brake			WSK-M06P-CA			
	1	Without brake	1.3kW		WSK-M04P-CA			
		With brake			WSK-M06P-CA			

Peripheral equipment

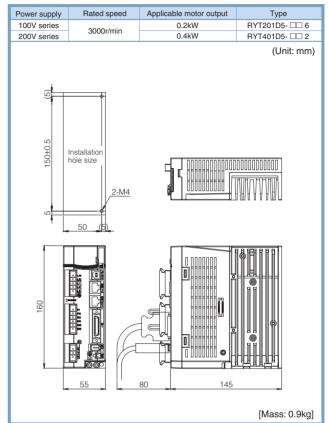
Rated speed	Input power supply	Servo amplifier type	Output of applied motor [kW]	Power supply capacity [kVA]	Input current [A]	Power filter	AC reactor	DC reactor	Molded case circuit breaker	Ground fault interruptor	Electromagnetic contactor
3000r/min	Single-phase 100V	RYT500D5- □□6	0.05	0.1	1.5	DNIETCOC 00	ACR2-0.4A	DCR2-0.4	EA32AC/3	EG32AC/3	
		RYT101D5- □□6	0.1	0.2	2.6	RNFTC06-20	ACR2-0.75A	DCR2-0.75	EA32AC/5	EG32AC/5	SC-03
		RYT201D5- □□6	0.2	0.4	4.8	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA32AC/10	EG32AC/10	
		RYT401D5- □□6	0.375	0.8	8.7	RNFTC20-20	ACR2-2.2A	DCR2-2.2	EA32AC/15	EG32AC/15	SC-0
	Single-phase 200V	RYT500D5- □□2	0.05	0.1	0.7		ACR2-0.4A	DCR2-0.2	EA32AC/3	EG32AC/3	
		RYT101D5- □□2	0.1	0.2	1.3	RNFTC06-20		DCR2-0.4			SC-03
		RYT201D5- □□2	0.2	0.4	2.4		ACR2-0.75A	DCR2-0.75	EA32AC/5	EG32AC/5] 30-03
		RYT401D5- □□2	0.4	0.8	4.7	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA32AC/10	EG32AC/10	
		RYT751D5- □□2	0.75	1.5	8.6	RNFTC20-20	ACR2-2.2A	DCR2-2.2	EA32AC/15	EG32AC/15	SC-0
	3-phase 200V	RYT500D5- □□2	0.05	0.1	0.4			DCR2-0.2			
		RYT101D5- □□2	0.1	0.2	0.7	RNFTC06-20	ACR2-0.4A	DCR2-0.2	EA33AC/3	EG33AC/3	
		RYT201D5- □□2	0.2	0.4	1.4	RINF CU6-20		DCR2-0.4			00.00
		RYT401D5- □□2	0.4	0.8	2.7		ACR2-0.75A	DCR2-0.75	EA33AC/5	EG33AC/5	SC-03
		RYT751D5- □□2	0.75	1.5	5.0	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA33AC/10	EG33AC/10	
		RYT102D5- □□2	1.0	2.0	6.6		4000000	DODO 0 0	EA33AC/15	EG33AC/15	1
		RYT152D5- □□2	1.5	2.9	9.8	DNETOOS OS	ACR2-2.2A	DCR2-2.2	EA33AC/20	EG33AC/20	SC-4-1
		RYT202D5- □□2	2.0	3.9	13.0	RNFTC20-20	ACR2-3.7A	DCR2-3.7	EA33AC/30	EG33AC/30	SC-4-1
		RYT302D5- □□2	3.0	5.9	19.5	RNFTC30-20	ACR2-5.5A	DCR2-5.5	EA53AC/40	EG53AC/40	SC-N1
		RYT402D5- □□2	4.0	7.8	26.0	DUETOES SS	ACR2-7.5A	DCR2-7.5	EA53AC/50	EG53AC/50	00.00
		RYT502D5- □□2	5.0	9.8	32.5	RNFTC50-20	ACR2-11A	DCR2-11	EA53AC/50	EG53AC/50	SC-N2
2000r/min	Single-phase 200V	RYT501C5- □□2	0.5	1.0	5.8	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA32AC/10	EG32AC/10	SC-03
		RYT751C5- □□2	0.75	1.5	8.6	RNFTC20-20	ACR2-2.2A	DCR2-2.2	EA32AC/15	EG32AC/15	SC-0
	3-phase 200V	RYT501C5- □□2	0.5	1.0	3.3	RNFTC06-20	ACR2-0.75A	DCR2-0.75		50001040	
		RYT751C5- □□2	0.75	1.5	5.0		ACR2-1.5A	DCR2-1.5	EA33AC/10	EG33AC/10	SC-03
		RYT102C5- □□2	1.0	2.0	6.6	RNFTC10-20			EA33AC/15	EG33AC/15	1
		RYT152C5- □□2	1.5	2.9	9.8		ACR2-2.2A	DCR2-2.2	EA33AC/20	EG33AC/20	
		RYT202C5- □□2	2.0	3.9	13.0	RNFTC20-20	ACR2-3.7A	DCR2-3.7	EA33AC/30	EG33AC/30	SC-4-1
1500r/min	Single-phase 200V	RYT501B5- □□2	0.5	1.0	5.8	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA32AC/10	EG32AC/10	SC-03
	3-phase 200V	RYT501B5- □□2	0.5	1.0	3.3	RNFTC06-20	ACR2-0.75A	DCR2-0.75			
	phase 2507	RYT851B5- □□2	0.85	1.7	5.6	RNFTC10-20	ACR2-1.5A	DCR2-1.5	EA33AC/10	EG33AC/10	SC-03
		RYT132B5- □□2	1.3	2.6	8.5	RNFTC20-20	ACR2-2.2A	DCR2-2.2	EA33AC/15	EG33AC/15	SC-0

Servo amplifier

■Frame 1



■Frame 2



■Frame 3

Power supply	Rated speed	Applicable motor output	Type						
100V series	3000r/min	0.375kW	RYT401D5- □□ 6						
	1500r/min	0.5kW	RYT501B5- □□ 2						
200V series	2000r/min	0.5kW	RYT501C5- □□ 2						
200 V 361163		0.75kW	RYT751C5- □□ 2						
	3000r/min	0.75kW	RYT751D5- □□ 2						
<u> </u>	(Unit: mm)								
150+0.55	4-M4 4-M4 35 80±0.5 (5)								
160	70	80	[Mass: 1.3kg]						

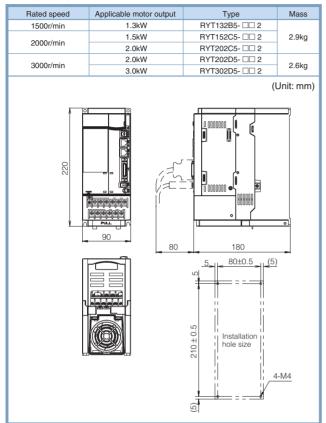
■Frame 4

Rated speed	Applicable motor output	Туре	
1500r/min	0.85kW	RYT851B5- □□ 2	
2000r/min	1.0kW	RYT102C5- □□ 2	
3000r/min	1.0kW	RYT102D5- □□ 2	
30001/111111	1.5kW	RYT152D5- □□ 2	
9 Installation hole size		RYT152D5- 🗆 2 (Unit: mm)	
80	80	145	
		[Mass: 1.4kg]	

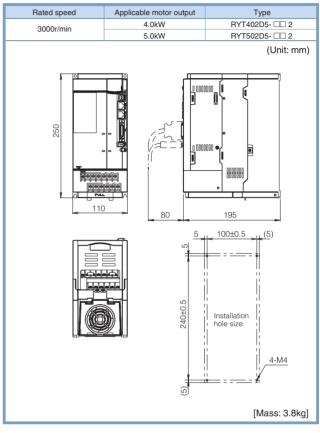


Servo amplifier

■Frame 5

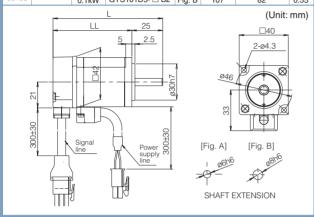


■Frame 6

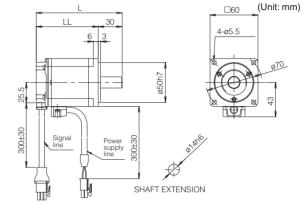


GYS Motor

Power	Rated	Rated	Type	Shaft	Over length	Dimensions(flange)	Mass
supply	speed	output	Туре	shape	L	LL	[kg]
100V		0.05kW	GYS500D5- □ B6	Fig. A	89	64	0.45
series	3000r/min	0.1kW	GYS101D5- □ B6	Fig. B	107	82	0.55
200V		0.05kW	GYS500D5- □ B2	Fig. A	89	64	0.45
series		0.1kW	GYS101D5- ☐ B2	Fig. B	107	82	0.55



Power supply	Rated speed	Rated output	Туре	Over length L	Dimensions(flange)	Mass [kg]
100V		0.2kW	GYS201D5- □ B6	107.5	77.5	1.2
series	3000r/min	0.375kW	GYS401D5- ☐ B6	135.5	105.5	1.8
200V	30001/111111	0.2kW	GYS201D5- ☐ B2	107.5	77.5	1.2
series		0.4kW	GYS401D5- □ B2	135.5	105.5	1.8



198

Over length Dimensions(flange) Terminal

LL

153

KB1

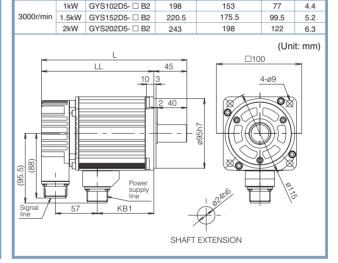
77

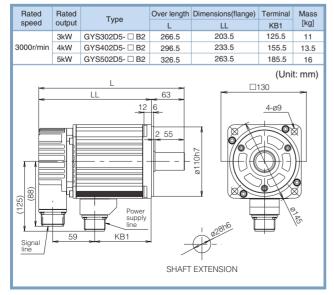
4.4

Rated output

Туре

Rated speed	Rated output	Type
3000r/min 16 121	0.75kW	GYS751D5- B2 (Unit: mm)
		[Mass: 3.4kg]



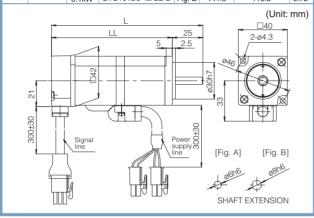


^{*} See page 32 for the shaft extension specifications of the motor with a key.

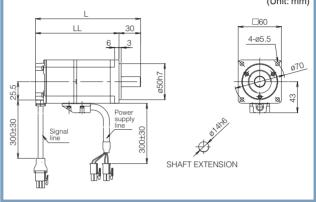


GYS Motor (With a brake)

Power	Rated	Rated	Туре	Shaft	Over length	Dimensions(flange)	Mass [kg]
	оросс			J.1101P	L	LL	[9]
100V series	0.05kW	GYS500D5- □ B6-B	Fig. A	123.5	98.5	0.62	
	3000r/min	0.1kW	GYS101D5- ☐ B6-B	Fig. B	141.5	116.5	0.72
200V		0.05kW	GYS500D5- ☐ B2-B	Fig. A	123.5	98.5	0.62
series		0.1kW	GYS101D5- ☐ B2-B	Fig. B	141.5	116.5	0.72



Power supply	Rated speed	Rated output	Туре	Over length L	Dimensions(flange)	Mass [kg]		
100V		0.2kW	GYS201D5- ☐ B6-B	145.5	115.5	1.7		
series	3000r/min	0.375kW	GYS401D5- ☐ B6-B	173.5	143.5	2.3		
200V	0.2kW	GYS201D5- ☐ B2-B	145.5	115.5	1.7			
series		0.4kW	GYS401D5- □ B2-B	173.5	143.5	2.3		
	(Unit: mm)							
LL 30								



Over length Dimensions(flange) Terminal Mass

Rated

Rated

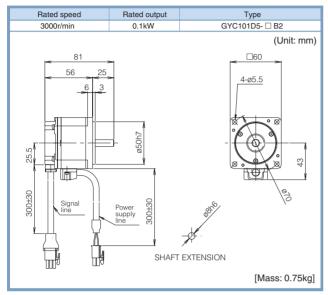
Rated speed	Rated output	Туре
3000r/min	0.75kW	GYS751D5- □ B2-B
3000r/min	Power supply line of the supply	GYS751D5- B2-B (Unit: mm)
		[Mass: 4.2kg]

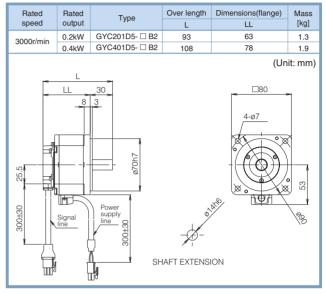
speed	output	.,,,,,	L	LL	KB1	[kg]
	1kW	GYS102D5- ☐ B2-B	239	194	79	5.9
3000r/min	1.5kW	GYS152D5- □ B2-B	261.5	216.5	101.5	6.8
	2kW	GYS202D5- □ B2-B	284	239	124	7.9
(88) Signal line	Poww	L	45 10 3		(Unit:	mm)

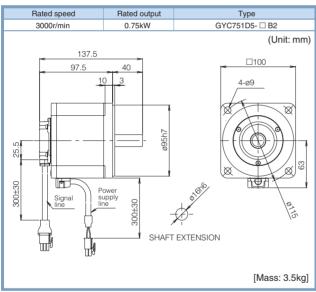
Rated speed	Rated output	Туре	Over length	Dimensions(flange)	Terminal KB1	Mass [kg]
	3kW	GYS302D5- □ B2-B	308.5	245.5	127.5	13
3000r/min	4kW	GYS402D5- ☐ B2-B	338.5	275.5	157.5	15.5
	5kW	GYS502D5- ☐ B2-B	368.5	305.5	187.5	18
Signal	5KW	L LL 12	63 6 2 55	1	(Unit:	mm)
			SHAFT	I EXTENSION		

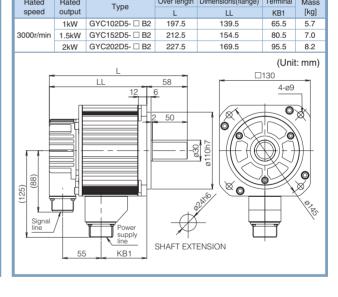
 $[\]ensuremath{^*}$ See page 32 for the shaft extension specifications of the motor with a key.

GYC Motor







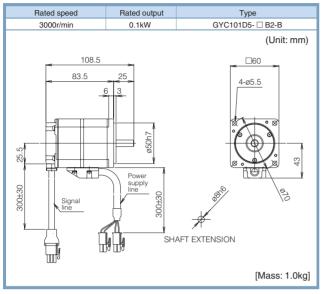


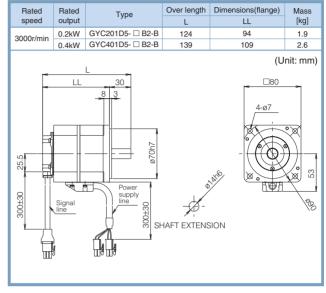
Over length | Dimensions(flange) | Terminal

^{*} See page 32 for the shaft extension specifications of the motor with a key.

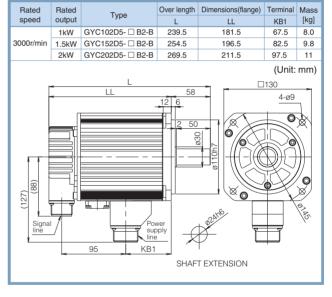


GYC Motor (With a brake)





Rated speed	Rated output	Type
3000r/min	0.75kW	GYC751D5- □ B2-B
		(Unit: mm)
169.5 129.5	Power supply line 000 SHAF	T EXTENSION [Mass: 4.3kg]



^{*} See page 32 for the shaft extension specifications of the motor with a key.

GYG Motor [2000r/min]

Rated speed	Rated output	Туре	Over length L	Dimensions(flange)	Terminal KB1	Mass [kg]
2000r/min	0.5kW	GYG501C5- ☐ B2	175	120	47.5	5.3
20001/111111	0.75kW	GYG751C5- ☐ B2	187.5	132.5	60	6.4
(011) Signal line	53	12 6	47 247 AAFT EXTEN		(Unit:	

speed	output	Type	L	LL	KB1	[kg]
	1kW	GYG102C5- ☐ B2	200	145	72.5	7.5
2000r/min	1.5kW	GYG152C5- ☐ B2	225	170	97.5	9.8
	2kW	GYG202C5- ☐ B2	250	195	122.5	12
					(Uni	t: mm)
		1			□130	
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<u> </u>	$/\!\!\perp$	Power supply			₩ \	'Q'
Signal /	/	line				
line /	5	3.5 KB1	SHAFT EX	TENSION		
	-	>1< >	•			

Over length Dimensions(flange) Terminal Mass

Over length Dimensions(flange) Terminal L LL KB1 [kg]

187.5

KB1

77

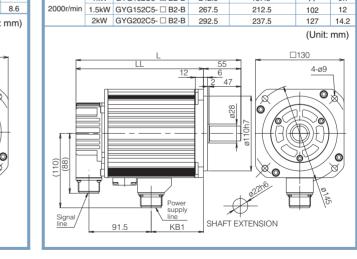
9.7

Rated Rated

Rated

GYG Motor [2000r/min] (With a brake)

Rated	Rated	Type		Dimensions(flange)	Terminal	Mass
speed	output	.,,,,	L	LL	KB1	[kg]
2000r/min	0.5kW	GYG501C5- ☐ B2-B	217.5	162.5	52	7.5
20001/111111	0.75kW	GYG751C5- ☐ B2-B	230	175	64.5	8.6
(110)	0.75kW	L LL 12	230 55 6 2 47	175	(Unit:	mm)
Signal / line		91.5 KB1		EXTENSION		



1kW GYG102C5- 🗆 B2-B 242.5

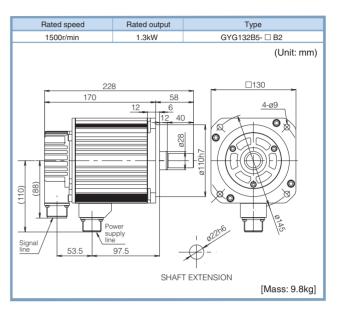
^{*} See page 32 for the shaft extension specifications of the motor with a key.

^{*} See page 32 for the shaft extension specifications of the motor with a key.



GYG Motor [1500r/min]

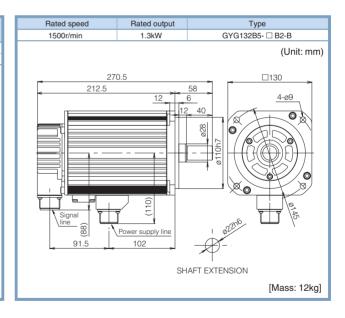
Rated speed	Rated output	Туре	Over length	Dimensions(flange)	Terminal KB1	Mass [kg]				
1500r/min	0.5kW	GYG501B5- □ B2	190.5	132.5	60	6.4				
13001/111111	0.85kW	GYG851B5- □ B2	203	145	72.5	7.5				
	(Unit: mm)									
12 40 4-Ø9										
Power supply sup										



GYG Motor [1500r/min] (With a brake)

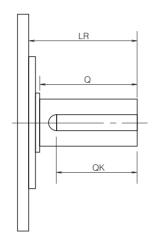
Rated speed	Rated output	Туре	Over length	Dimensions(flange)	Terminal	Mass [kg]
эреец		01/050/05 5 5 5 5	L	LL	KB1	-
1500r/min	0.5kW	GYG501B5- □ B2-B	233	175	64.5	8.6
	0.85kW	GYG851B5- □ B2-B	245.5	187.5	77	9.7
					(Unit:	mm)
(110)	Sig		58 6 12 40 88 80 SHAFT	ZHOLLO WAS TENSION	4-ø9	© 88

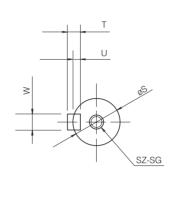




^{*} See page 32 for the shaft extension specifications of the motor with a key.

Shaft Extension Specifications (wiht a key, tapped)





Motor type	LR	Q	QK	S	Т	U	W	SZ	SG
GYS Motor									
GYS500D5-□A□-□ *1	25	-	14	ø6h6	2	1.2	2	-	-
GYS101D5-□A□-□ *1				ø8h6	3	1.8	3	-	-
GYS201D5-□C□-□	30		20	ø14h6	5	3	5	M5	8
GYS401D5-□C□-□									
GYS751D5-□C2-□	40		30	ø16h6					
GYS102D5-□C2-□	45	40	32	ø24h6	7	4	8	M8	16
GYS152D5-□C2-□									
GYS202D5-□C2-□									
GYS302D5-□C2-□	63	55	45	ø28h6					
GYS402D5-□C2-□									
GYS502D5-□C2-□									
GYC Motor									
GYC101D5-□A2-□ *1	25	-	14	ø8h6	3	1.8	3	-	-
GYC201D5-□C2-□	30		16	ø14h6	5	3	5	M5	8
GYC401D5-□C2-□									
GYC751D5-□C2-□	40		22	ø16h6					
GYC102D5-□C2-□	58	50	40	ø24h6	7	4	8	M8	16
GYC152D5-□C2-□									
GYC202D5-□C2-□									
GYG Motor 2000r/min									
GYG501C5-□C2-□	55	47	35	ø19h6	6	3.5	6	M6	12
GYG751C5-□C2-□									
GYG102C5-□C2-□				ø22h6	7	4	8	M8	16
GYG152C5-□C2-□									
GYG202C5-□C2-□									
GYG Motor 1500r/min									
GYG501B5-□C2-□	58	40	30	ø19h6	6	3.5	6	M6	12
GYG851B5-□C2-□									
GYG132B5-□C2-□				ø22h6	7	4	8	M8	16

^{*1} The shaft extension of the GYS and GYC motors of 0.1kW or less is not tapped.



Servo amplifier

Specifica	ations					5	_
Model	Control mode	Command interface	Input power supply	Applicable motor	Applicable motor output	Product code	Туре
VV type	Position, speed and	General-purpose	Single-phase or 3-phase 200 to 240V	GYS, GYC motor	0.05kW	RYT1201	RYT500D5-VV2
	torque control	interface		3000r/min	0.1kW	RYT1202	RYT101D5-VV2
	(With built-in linear	(pulse or			0.2kW	RYT1203	RYT201D5-VV2
	positioning function)	analog voltage)			0.4kW	RYT1204	RYT401D5-VV2
		(Di/Do)			0.75kW	RYT1205	RYT751D5-VV2
		(Modbus-RTU)	3-phase 200 to 240V		1.0kW	RYT1206	RYT102D5-VV2
					1.5kW	RYT1207	RYT152D5-VV2
					2.0kW	RYT1208	RYT202D5-VV2
					3.0kW	RYT1209	RYT302D5-VV2
					4.0kW	RYT1210	RYT402D5-VV2
			0.501	CVCt	5.0kW	RYT1211	RYT502D5-VV2
			Single-phase 100V	GYS motor	0.05kW	RYT3251	RYT500D5-VV6
				3000r/min	0.1kW	RYT3252	RYT101D5-VV6
					0.2kW 0.375kW	RYT3253	RYT201D5-VV6
			Single-phase or 3-phase 200 to 240V	GYG motor		RYT3254	RYT401D5-VV6
			Single-phase of 3-phase 200 to 240V	2000r/min	0.5kW	RYT1231	RYT501C5-VV2
			2 phase 200 to 240V	2000//////	0.75kW	RYT1232	RYT751C5-VV2
			3-phase 200 to 240V		1.0kW	RYT1233	RYT102C5-VV2
					1.5kW 2.0kW	RYT1234	RYT152C5-VV2
			Single-phase or 3-phase 200 to 240V	GYG motor	0.5kW	RYT1235	RYT202C5-VV2
			3-phase 200 to 240V	1500r/min	0.85kW	RYT3261 RYT3262	RYT501B5-VV2
			3-priase 200 to 240 v	13001/111111	1.3kW		RYT851B5-VV2
VS type	Position, speed and	High speed serial	Single-phase or 3-phase 200 to 240V	GYS, GYC motor	0.05kW	RYT3263 RYT1001	RYT132B5-VV2 RYT500D5-VS2
vo type	torque control	bus (SX bus)	Single-phase of 3-phase 200 to 240V	3000r/min	0.1kW	RYT1001	RYT101D5-VS2
	torque contror	bus (ox bus)			0.1kW	RYT1002	RYT201D5-VS2
					0.4kW	RYT1003	RYT401D5-VS2
					0.75kW	RYT1005	RYT751D5-VS2
			3-phase 200 to 240V	-	1.0kW	RYT1006	RYT102D5-VS2
			o pridoc 200 to 2 for		1.5kW	RYT1007	RYT152D5-VS2
					2.0kW	RYT1008	RYT202D5-VS2
					3.0kW	RYT1009	RYT302D5-VS2
					4.0kW	RYT1010	RYT402D5-VS2
					5.0kW	RYT1011	RYT502D5-VS2
			Single-phase 100V	GYS motor 3000r/min	0.05kW	RYT3051	RYT500D5-VS6
					0.1kW	RYT3052	RYT101D5-VS6
					0.2kW	RYT3053	RYT201D5-VS6
					0.375kW	RYT3054	RYT401D5-VS6
			Single-phase or 3-phase 200 to 240V	GYG motor	0.5kW	RYT1031	RYT501C5-VS2
				2000r/min	0.75kW	RYT1032	RYT751C5-VS2
			3-phase 200 to 240V		1.0kW	RYT1033	RYT102C5-VS2
					1.5kW	RYT1034	RYT152C5-VS2
					2.0kW	RYT1035	RYT202C5-VS2
			Single-phase or 3-phase 200 to 240V	GYG motor	0.5kW	RYT3061	RYT501B5-VS2
			3-phase 200 to 240V	1500r/min	0.85kW	RYT3062	RYT851B5-VS2
					1.3kW	RYT3063	RYT132B5-VS2
LS type	Position control	High speed serial	Single-phase or 3-phase 200 to 240V	GYS, GYC motor	0.05kW	RYT3101	RYT500D5-LS2
	(With built-in linear	bus (SX bus)		3000r/min	0.1kW	RYT3102	RYT101D5-LS2
	positioning function)				0.2kW	RYT3103	RYT201D5-LS2
					0.4kW	RYT3104	RYT401D5-LS2
				1	0.75kW	RYT3105	RYT751D5-LS2
			3-phase 200 to 240V		1.0kW	RYT3106	RYT102D5-LS2
					1.5kW	RYT3107	RYT152D5-LS2
					2.0kW	RYT3108	RYT202D5-LS2
					3.0kW	RYT3109	RYT302D5-LS2
					4.0kW	RYT3110	RYT402D5-LS2
			Circle above 100V	CVC1	5.0kW	RYT3111	RYT502D5-LS2
			Single-phase 100V	GYS motor	0.05kW	RYT3151	RYT500D5-LS6
				3000r/min	0.1kW	RYT3152	RYT101D5-LS6
					0.2kW	RYT3153	RYT201D5-LS6
			Single phase or 2 phase 200 to 040V	GVG motor	0.375kW	RYT3154	RYT401D5-LS6
			Single-phase or 3-phase 200 to 240V	GYG motor	0.5kW	RYT3131	RYT501C5-LS2
			3-phase 200 to 240V	2000r/min	0.75kW	RYT3132	RYT751C5-LS2
			3-priase 200 to 240V		1.0kW	RYT3133	RYT102C5-LS2
					1.5kW	RYT3134	RYT152C5-LS2
			Single-phase or 3-phase 200 to 240V	GYG motor	2.0kW	RYT3135	RYT202C5-LS2
			3-phase 200 to 240V	1500r/min	0.5kW	RYT3161	RYT501B5-LS2
			5 priaso 200 to 240 V	1000//111111	0.85kW	RYT3162	RYT851B5-LS2
	1	<u> </u>		1	1.3kW	RYT3163	RYT132B5-LS2

Servomotor

Specifications	Malka	Datad	Oil seel/sheft	Frank	Duelee	Detect : 1: 1	Product code	Туре
Model	Voltage	Rated speed	Oil seal/shaft	Encoder	Brake	Rated output 0.05kW	GYS1301	GYS500D5-HB2
/S motor	200V	3000r/min	Without an oil seal and a key (*1)	18-bit ABS/INC	Without a brake			
ultra low inertia)						0.1kW	GYS1302	GYS101D5-HB2
						0.2kW	GYS1303	GYS201D5-HB2
						0.4kW	GYS1304	GYS401D5-HB2
						0.75kW	GYS1305	GYS751D5-HB2
						1.0kW	GYS1306	GYS102D5-HB2
						1.5kW	GYS1307	GYS152D5-HB2
						2.0kW	GYS1308	GYS202D5-HB2
						3.0kW	GYS1309	GYS302D5-HB2
						4.0kW	GYS1310	GYS402D5-HB2
						5.0kW	GYS1311	GYS502D5-HB2
					With a brake	0.05kW	GYS1321	GYS500D5-HB2-
						0.1kW	GYS1322	GYS101D5-HB2
						0.2kW	GYS1323	GYS201D5-HB2
						0.4kW	GYS1324	GYS401D5-HB2
						0.75kW	GYS1325	GYS751D5-HB2
						1.0kW	GYS1326	GYS102D5-HB2
						1.5kW		
							GYS1327	GYS152D5-HB2
		1				2.0kW	GYS1328	GYS202D5-HB2
						3.0kW	GYS1329	GYS302D5-HB2
						4.0kW	GYS1330	GYS402D5-HB2-
						5.0kW	GYS1331	GYS502D5-HB2-
				20-bit INC	Without a brake	0.05kW	GYS1341	GYS500D5-RB2
						0.1kW	GYS1342	GYS101D5-RB2
						0.2kW	GYS1343	GYS201D5-RB2
						0.4kW	GYS1344	GYS401D5-RB2
						0.75kW	GYS1345	GYS751D5-RB2
						1.0kW	GYS1346	GYS102D5-RB2
						1.5kW	GYS1347	GYS152D5-RB2
						2.0kW	GYS1348	GYS202D5-RB2
						3.0kW	GYS1349	GYS302D5-RB2
						4.0kW	GYS1350	GYS402D5-RB2
						5.0kW	GYS1351	GYS502D5-RB2
					With a brake	0.05kW	GYS1361	GYS500D5-RB2-
						0.1kW	GYS1362	GYS101D5-RB2
						0.2kW	GYS1363	GYS201D5-RB2
						0.4kW	GYS1364	GYS401D5-RB2
						0.75kW	GYS1365	GYS751D5-RB2-
						1.0kW	GYS1366	GYS102D5-RB2-
						1.5kW	GYS1367	GYS152D5-RB2
		1				2.0kW	GYS1368	GYS202D5-RB2
		1				3.0kW	GYS1369	GYS302D5-RB2-
		1				4.0kW	GYS1370	GYS402D5-RB2-
		1				5.0kW	GYS1371	GYS502D5-RB2-
	1001/	2000-/:-	Without an oil seal and a key (*1)	10 1-1 100/110	Mithout - II			
	100V	3000r/min	viniout an oil seal and a key (*1)	18-bit ABS/INC	Without a brake	0.05kW 0.1kW	GYS1601	GYS500D5-HB6
							GYS1602	GYS101D5-HB6
						0.2kW	GYS1603	GYS201D5-HB6
		1				0.375kW	GYS1604	GYS401D5-HB6
		1			With a brake	0.05kW	GYS1621	GYS500D5-HB6
						0.1kW	GYS1622	GYS101D5-HB6
						0.2kW	GYS1623	GYS201D5-HB6
		1				0.375kW	GYS1624	GYS401D5-HB6
		1		20-bit INC	Without a brake	0.05kW	GYS1641	GYS500D5-RB6
		1				0.1kW	GYS1642	GYS101D5-RB6
		1				0.2kW	GYS1643	GYS201D5-RB6
		1				0.375kW	GYS1644	GYS401D5-RB6
		1			With a brake	0.05kW	GYS1661	GYS500D5-RB6-
		1			Will a blake	0.1kW	GYS1662	GYS101D5-RB6-
				i .	I .	U. IKVV	0101002	01010100-nB6-
						0.2kW	GYS1663	GYS201D5-RB6-

^{*1:} The motor with a shaft extension with a key and tapped is available as a semi-standard item. (See page 32 for shaft extension specifications.)

The other specifications are handled as a made-to-order item.



Servomotor

Specifications							Dun dunt no d	Tomas
Model	Voltage	Rated speed	Oil seal/shaft	Encoder	Brake	Rated output	Product code	Туре
GYC motor	200V	3000r/min	Without an oil seal and a key (*1)	18-bit ABS/INC	Without a brake	0.1kW	GYC1301	GYC101D5-HB2
low inertia)						0.2kW	GYC1302	GYC201D5-HB2
						0.4kW	GYC1303	GYC401D5-HB2
						0.75kW	GYC1304	GYC751D5-HB2
						1.0kW	GYC1305	GYC102D5-HB2
						1.5kW	GYC1306	GYC152D5-HB2
						2.0kW	GYC1307	GYC202D5-HB2
					With a brake	0.1kW	GYC1321	GYC101D5-HB2-B
						0.2kW	GYC1322	GYC201D5-HB2-B
						0.4kW	GYC1323	GYC401D5-HB2-B
						0.75kW	GYC1324	GYC751D5-HB2-B
						1.0kW	GYC1325	GYC102D5-HB2-B
						1.5kW	GYC1326	GYC152D5-HB2-B
						2.0kW	GYC1327	GYC202D5-HB2-B
				20-bit INC	Without a brake	0.1kW	GYC1341	GYC101D5-RB2
						0.2kW	GYC1342	GYC201D5-RB2
						0.4kW	GYC1343	GYC401D5-RB2
						0.75kW	GYC1344	GYC751D5-RB2
						1.0kW	GYC1345	GYC102D5-RB2
						1.5kW	GYC1346	GYC152D5-RB2
						2.0kW	GYC1347	GYC202D5-RB2
					With a brake	0.1kW	GYC1361	GYC101D5-RB2-B
						0.2kW	GYC1362	GYC201D5-RB2-B
						0.4kW	GYC1363	GYC401D5-RB2-B
						0.75kW	GYC1364	GYC751D5-RB2-B
						1.0kW	GYC1365	GYC102D5-RB2-B
						1.5kW	GYC1366	GYC152D5-RB2-B
						2.0kW	GYC1367	GYC202D5-RB2-B
GYG motor	200V	2000r/min	Without an oil seal and a key (*1)	18-bit ABS/INC	Without a brake	0.5kW	GYG1301	GYG501C5-HB2
(medium inertia)						0.75kW	GYG1302	GYG751C5-HB2
						1.0kW	GYG1303	GYG102C5-HB2
						1.5kW	GYG1304	GYG152C5-HB2
						2.0kW	GYG1305	GYG202C5-HB2
					With a brake	0.5kW	GYG1321	GYG501C5-HB2-B
						0.75kW	GYG1322	GYG751C5-HB2-B
						1.0kW	GYG1323	GYG102C5-HB2-B
						1.5kW	GYG1324	GYG152C5-HB2-B
						2.0kW	GYG1325	GYG202C5-HB2-B
				20-bit INC	Without a brake	0.5kW	GYG1401	GYG501C5-RB2
						0.75kW	GYG1402	GYG751C5-RB2
						1.0kW	GYG1403	GYG102C5-RB2
						1.5kW	GYG1404	GYG152C5-RB2
						2.0kW	GYG1405	GYG202C5-RB2
					With a brake	0.5kW	GYG1421	GYG501C5-RB2-B
					1 2.3.4.10	0.75kW	GYG1422	GYG751C5-RB2-B
						1.0kW	GYG1423	GYG102C5-RB2-B
						1.5kW	GYG1424	GYG152C5-RB2-B
						2.0kW	GYG1425	GYG202C5-RB2-B
GYG motor	200V	1500r/min	Without an oil seal and a key (*1)	18-bit ABS/INC	Without a brake	0.5kW	GYG1501	GYG501B5-HB2
(medium inertia)			Williout air oir sear airu a key (1)			0.85kW	GYG1502	GYG851B5-HB2
(modium intentia)						1.3kW	GYG1502	GYG132B5-HB2
					With a brake	0.5kW	GYG1503	GYG501B5-HB2-B
					.viai a biano	0.85kW	GYG1521	GYG851B5-HB2-B
						1.3kW	GYG1522 GYG1523	GYG132B5-HB2-B
				20-bit INC	Without a brake			GYG501B5-RB2
				בט-טונ וואכ	vvitriout a brake	0.5kW	GYG1601	
						0.85kW	GYG1602	GYG851B5-RB2
					Mish a b l	1.3kW	GYG1603	GYG132B5-RB2
					With a brake	0.5kW	GYG1621	GYG501B5-RB2-B
						0.85kW	GYG1622	GYG851B5-RB2-B
	1					1.3kW	GYG1623	GYG132B5-RB2-B

^{*1:} The motor with a shaft extension with a key and tapped is available as a semi-standard item. (See page 32 for shaft extension specifications.)

The other specifications are handled as a made-to-order item.

Option

■Connector and cable

Name			Specifications	Product code	Туре	
For main circuit of		er control power and main power supply)	0.05 to 1.5kW (to 1.0kW with GYG)	1 set	RYWS043	WSK-S05P-E
amplifier	DC circuit connector (wiring of external re	generative resistor, DC reactor, DC link circuit) *1	0.05 to 1.5kW (to 1.0kW with GYG)	1 set	RYWS044	WSK-R06P-E
	Motor power connector (wiring	of main motor power)	0.05 to 1.5kW (to 1.0kW with GYG)	1 set	RYWS045	WSK-M03P-E
For sequence I/O	Sequence I/O cable		All capacities	3m (bare wires on one side)	RYWS802	WSC-D36P03
between host and amplifier	Sequence I/O connector kit *4		Amplifier side : All capacities	1 set	RYWS022	WSK-D36P
For encoder	Encoder cable		3000r/min for 0.05 to 0.75kW	2m (connector at both ends)	RYWS862	WSC-P06P02-E
(between amplifier				5m (connector at both ends)	RYWS863	WSC-P06P05-E
and motor)				10m (connector at both ends)	RYWS864	WSC-P06P10-E
				20m (connector at both ends)	RYWS865	WSC-P06P20-E
			3000r/min for 1.0 to 5.0kW	5m (connector at both ends)	RYWS806	WSC-P06P05-C
			2000r/min for 0.5 to 2.0kW	10m (connector at both ends)	RYWS807	WSC-P06P10-C
			1500r/min for 0.5 to 1.3kW	20m (connector at both ends)	RYWS808	WSC-P06P20-C
	Encoder connector kit *4		Amplifier side : All capacities	1 set	RYWS023	WSK-P06P-M
			Motor side: 0.05 to 0.75kW	1 set	RYWS036	WSK-P09P-D
			Motor side : 0.5 to 5.0kW	1 set	RYWS025	WSK-P06P-C
For motor power	Motor power cable	For main motor power *2	GYS, GYC: 0.05 to 0.75kW	2m (bare wires on one side)	RYWS868	WSC-M04P02-E
(between amplifier				5m (bare wires on one side)	RYWS869	WSC-M04P05-E
and motor)				10m (bare wires on one side)	RYWS870	WSC-M04P10-E
				20m (bare wires on one side)	RYWS871	WSC-M04P20-E
		For brake power *3	GYS, GYC: 0.05 to 0.75kW	2m (bare wires on one side)	RYWS874	WSC-M02P02-E
				5m (bare wires on one side)	RYWS875	WSC-M02P05-E
				10m (bare wires on one side)	RYWS876	WSC-M02P10-E
				20m (bare wires on one side)	RYWS877	WSC-M02P20-E
	Motor power connector kit	For main motor power *4	Motor side: 0.05 to 0.75kW	1 set	RYWS046	WSK-M04P-E
		For brake power *4	Motor side: 0.05 to 0.75kW	1 set	RYWS047	WSK-M02P-E
		For main motor power *4	Motor side : GYS 1.0 to 2.0kW	1 set	RYWS027	WSK-M04P-CA
			GYG 0.5 to 2.0kW			
			Motor side : GYS 3.0 to 5.0kW	1 set	RYWS031	WSK-M04P-CB
			GYC 1.0 to 2.0kW			
		For main motor power	Motor side : GYS 1.0 to 2.0kW	1 set	RYWS029	WSK-M06P-CA
		+ brake power *4	GYG 0.5 to 2.0kW			
			Motor side : GYS 3.0 to 5.0kW	1 set	RYWS032	WSK-M06P-CB
			GYC 1.0 to 2.0kW			
For SX bus	SX bus cable		For VS and LS type	0.3m (connector at both ends)	NP1C001	NP1C-P3
			servo amplifiers	0.6m (connector at both ends)	NP1C002	NP1C-P6
			,	0.8m (connector at both ends)	NP1C003	NP1C-P8
				2m (connector at both ends)	NP1C004	NP1C-02
				5m (connector at both ends)	NP1C005	NP1C-05
				10m (connector at both ends)	NP1C006	NP1C-10
				15m (connector at both ends)	NP1C016	NP1C-15
				25m (connector at both ends)	NP1C007	NP1C-25

^{*1:} One connector is included in the accessory of the main body of the servo amplifier.

■Common options

Specifications	Product code	Туре				
ABS backup battery	Set of bat	tery and case (*With case)	RYWS007	WSB-SC		
	Battery	(*Discrete replacen	1 piece	RYWS003	WSB-S	
External regenerative resistor	200V	3000r/min for 0.05 to 0.4kW				WSR-401
		3000r/min for 0.75 to 1.5kW, 2000r/min for 0.5 to 1.0kW, 1500r/min for 0.5 to 0.85kW				WSR-152
		3000r/min for 2.0 to 3.0kW, 2000r/min 1.5 to 2.0kW, 1500r/min 1.3kW			RGWG339	DB11-2
		3000r/min for 4.0 to 5.0kW				DB22-2
	100V	3000r/min for 0.05 to 0.375kW	3000r/min for 0.05 to 0.375kW			
For PC loader connection	RS-232C -	- RS-485 conversion adaptor	For connection of RS-485 port	_	NW0H003	NW0H-CNV
	Cable	of VV type servo amplifier *1 2m (connector at both ends)			RYWS005	WSC-PCL

 $^{^{\}star} 1:$ Prepare a marketed USB cable (A-B type) for the USB port.

 $^{^{\}star}2:$ Use this cable with motor power connector (on amplifier side) WSK-M03P-E.

^{*3:} Use this cable as a brake cable of the motor equipped with a brake.

^{*4:} Use this connector when the customer fabricates a cable at arbitrary length.



Service Network



Fuji FA Service Centers

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- USA Service Center [Service Area: USA, Canada, Central & South America]
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- Phone: (714)220-1879
- CHICAGO Service Station
 4825 N. Scott St. Suite 210, Schiller Park, IL 60176
- Phone: (847)233-9844
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 [Service Area: Europe, Middle East & Africa] Goethering 58, 63067 Oftenbach/ Main Germany
- Phone: (69)669029-0
 South East Asia & Oceania Service Center [Service Area: SE & S Asia, Oceania] 171 Chin Swee Road, #12-01, San Centre, Singapore 169877 Phone: (6481)5079
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- **7** TAIWAN
- Full Key International Technology Ltd 12F, No.111-8, HSING TEH RD., SAN-CHUNG CITY, TAIPEI, TAIWAN Phone: (02)2995-2008
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To all our customers who purchase Fuji Electric products included in this catalog:

Please take the following items into consideration when placing your order.

When requesting an estimate and placing your orders for the products included in these materials, please be aware that any items such as specifications which are not specifically mentioned in the contract, catalog, specifications or other materials will be as mentioned below.

In addition, the products included in these materials are limited in the use they are put to and the place where they can be used, etc., and may require periodic inspection. Please confirm these points with your sales representative directly with this company.

Furthermore, regarding purchased products and delivered products, we request that you take adequate consideration of the necessity of rapid receiving inspections and of product management and maintenance even before receiving

1. Free of Charge Warranty Period and Warranty Range

1-1 Free of charge warranty period

- (1) The product warranty period is "1 year from the date of purchase" or 24 months from the manufacturing date imprinted on the name place, whichever date is earlier.

 (2) However, in cases where the use environment, conditions of use, use frequency and times used, etc., have an
- effect on product life, this warranty period may not apply
- (3) Furthermore, the warranty period for parts restored by Fuji Electric's Service Department is "6 months from the date that repairs are completed."

1-2 Warranty range

- (1) In the event that breakdown occurs during the product's warranty period which is the responsibility of Fuji Electric, Fuji Electric will replace or repair the part of the product that has broken down free of charge at the place where the product was purchased or where it was delivered. However, if the following cases are applicable, the terms of this warranty may not apply.
 - 1) The breakdown was caused by inappropriate conditions, environment, handling or use methods, etc. which are not specified in the catalog, operation manual, specifications or other relevant documents
 - 2) The breakdown was caused by the product other than the purchased or delivered Fuji's product.
 - 3) The breakdown was caused by the product other than Fuji's product, such as the customer's equipment or software design, etc.
 - 4) Concerning the Fuii's programmable products, the breakdown was caused by a program other than a program supplied by this company, or the results from using such a program.

 5) The breakdown was caused by modifications or repairs affected by a party other than Fuji Electric.

 - 6) The breakdown was caused by improper maintenance or replacement using consumables, etc. specified in the operation manual or catalog, etc.

 7) The breakdown was caused by a chemical or technical problem that was not foreseen when making practical
 - application of the product at the time it was purchased or delivered.
 - 8) The product was not used in the manner the product was originally intended to be used.
- 9) The breakdown was caused by a reason which is not this company's responsibility, such as lightning or other
- (2) Furthermore, the warranty specified herein shall be limited to the purchased or delivered product alone
- (3) The upper limit for the warranty range shall be as specified in item (1) above and any damages (damage to or loss of machinery or equipment, or lost profits from the same, etc.) consequent to or resulting from breakdown of the purchased or delivered product shall be excluded from coverage by this warranty.

1-3. Trouble diagnosis

As a rule, the customer is requested to carry out a preliminary trouble diagnosis. However, at the customer's request, this company or its service network can perform the trouble diagnosis on a chargeable basis. In this case, the customer is asked to assume the burden for charges levied in accordance with this company's fee schedule.

2. Exclusion of Liability for Loss of Opportunity, etc.

Regardless of whether a breakdown occurs during or after the free of charge warranty period, this company shall not be liable for any loss of opportunity, loss of profits, or damages arising from special circumstances. secondary damages, accident compensation to another company, or damages to products other than this company's products, whether foreseen or not by this company, which this company is not be responsible for causing

3. Repair Period after Production Stop, Spare Parts Supply Period (Holding Period)

Concerning models (products) which have gone out of production, this company will perform repairs for a period of 7 years after production stop, counting from the month and year when the production stop occurs. In addition, we will continue to supply the spare parts required for repairs for a period of 7 years, counting from the month and year when the production stop occurs. However, if it is estimated that the life cycle of certain electronic and other parts is short and it will be difficult to procure or produce those parts, there may be cases where it is difficult to provide repairs or supply spare parts even within this 7-year period. For details, please confirm at our company's business office or our service office

4. Transfer Rights

In the case of standard products which do not include settings or adjustments in an application program, the products shall be transported to and transferred to the customer and this company shall not be responsible for local adjustments or trial operation.

5. Service Contents

The cost of purchased and delivered products does not include the cost of dispatching engineers or service costs. Depending on the request, these can be discussed separately

6. Applicable Scope of Service

Above contents shall be assumed to apply to transactions and use of the country where you purchased the products. Consult the local supplier or Fuji for the detail separately



Reference Material

Motion controller **MICREX-SX Series SPH**

Various CPUs matching your purposes are included in the line of products.

- Module type (Up to 64 axes control)
 PCI bus compatible board type (Up to 32 axes control)
 Selection of program language best for the control (LD, ST or FB language)



Catalog (LEH982)

Programmable operation display **UG Series POD**

Various products ranging from 5.7" (QVGA) to 15" (XGA) types are included in the product line. Full color (32,768 colors) realizes colorful and beautiful screen expression.



Catalog (LEH854)



- 1. This catalog is intended for use in selecting required servo systems. Before actually using these products, carefully read their instruction manuals and understand their correct usage.
- 2. Products described in this catalog are neither designed nor manufactured for combined use with a system or equipment that will affect human lives.
 - If you are considering using these products for special purposes, such as atomic energy control, aerospace, medical application, or traffic control, please consult our sales office.
- 3. If you use our product with equipment that is expected to cause serious injury or damage to your property in case of failure, be sure to take appropriate safety measures for the equipment.

The Inverter Value Engineering Center (Suzuka Area) has acquired environment management system ISO14001 and quality management system ISO9001 certifications.











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